

CPS_CPS10 SYSTEM

Installation, Operation and Maintenance Guide





The Fixed Gas Detection People





Reference : NP CPS GB

Révision: G



The Fixed Gas Detection People

GAS DETECTION

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GUARANTEE

2 years guarantee in normal conditions of use on parts and technical labour, return in our workshops, excluding consumables (sensors, filters, etc.)

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General Information

Please read the following notice carefully before installation and start-up, paying particular attention to the end-user material safety instructions. This user's guide should be distributed to every individual involved in the installation, operation, maintenance or repair of the CPS system.

The information contained in this manual, the data and technical drawings are correct as of the date of publication. Should questions arise, please contact Industrial Scientific for additional information.

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This manual is a translation of the French original. In case of discrepancy between the French version and any translated version, the French version shall take precedence and shall prevail in all matters pertaining to any relationship between the parties.

This icon indicates that there is additional useful information for a particular topic.

Safety Warnings

Pictogram labels have been placed on the central controller to call attention to general use safety precautions. These labels are an integral component of the central controller. Replace any label that has peeled off or become illegible. The meanings of these labels are explained below.



Ground terminal



Safety ground terminal



Risk of electric shock



Caution (see accompanying documentation)



WARNING

The installation of this product and all electrical connections should be performed by a qualified professional, in accordance with the manufacturer's specifications and with the standards of authorities in the field.

Failure to observe these warnings may result in serious injury.
Exercise great caution, particularly when working with electricity during installation (couplings, network connections).



European Union (and EEA) only. This icon indicates that in accordance with Directive DEEE (2002/96/CE) and with the regulations specific to your country, this product may not be disposed of with household waste.

Dispose of this product at a collection site intended for electrical waste, for example an official EEE (electrical and electronic equipment) collection site with a recycling or take-back program for authorized products which are available to consumers whose purchases are intended to replace old EEE products with new equivalents.

Failure to comply with regulations for the disposal of this type of waste can be harmful to the environment and to public health, as EEE products typically contain substances that may be dangerous. Your complete cooperation with the disposal of this product will help to ensure a more efficient use of natural resources.

Important Information

The modification of any piece of equipment or the use of any third party parts will automatically void all guarantees.

The central controller is intended to be used for precise applications of a technical nature. Exceeding the indicated values is strictly prohibited.

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Chapter 1 Overview of the CPS System

The system consists of:

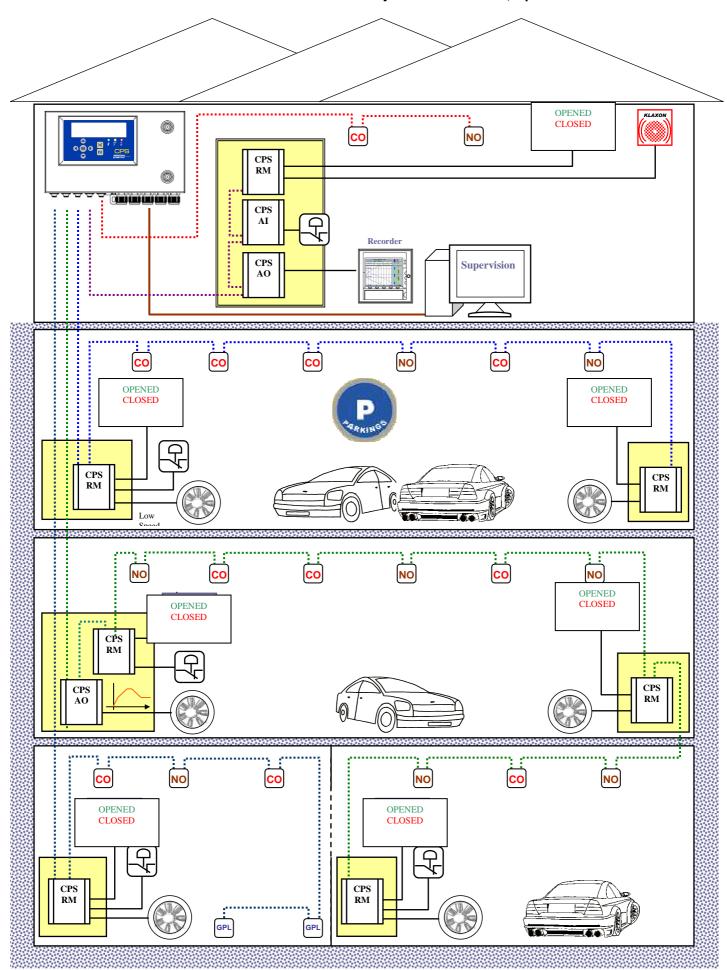
- a central controller for collecting readings and managing alarms;
- various addressable digital modules (sensor modules, relay modules, analog output modules, logic input modules);
- instruments and accessories to process alarms and actions

The CPS system can manage the detection of **10 different gases**, and all detectors are clearly localized and identified.

Data from each sensor is collected in the central controller in less than one second. If gas levels exceed the programmed limits, an audiovisual alarm is triggered and can activate the ventilation system in the affected area of the parking facility.

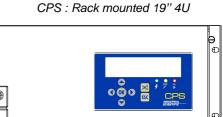
Use the COM_CPS software to program the central controller.

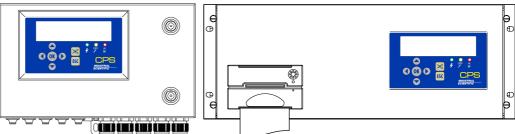
The system status can be quickly verified with semi-automatic calibration for various sensors.



The CPS central controller

CPS: Wall mounted version





The central controller is available in a 19" 4U (rack-mount) version or in a wall-mount version. It is designed to control:

- 256 digital modules distributed over 8 lines, with a maximum of 32 modules per line;
- 256 addressable relays max. distributed across all relay modules;
- 224 logic inputs max. distributed across all logic input modules and relay modules.
- 256 analog outputs max. distributed across 4 analog outputs modules.

Modules are connected through a digital RS-485 network using JBUS/MODBUS protocol.

The central controller connects to 256 toxic sensors, and runs on only 24 Watts.

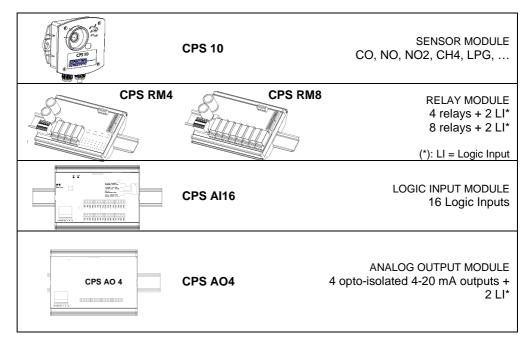
The central controller can be connected to a supervision system via an RS-485 output interface using ModBus protocol.

Optional features include:

- a battery back-up, ensuring continual operation in case of a power outage (approx. 1 hour for 50 TOX-type sensors);
- an integrated printer (rack-mounted version only) for recording alarms and events;
- an external printer (for both rack- and wall-mounted versions).

Digital addressable modules

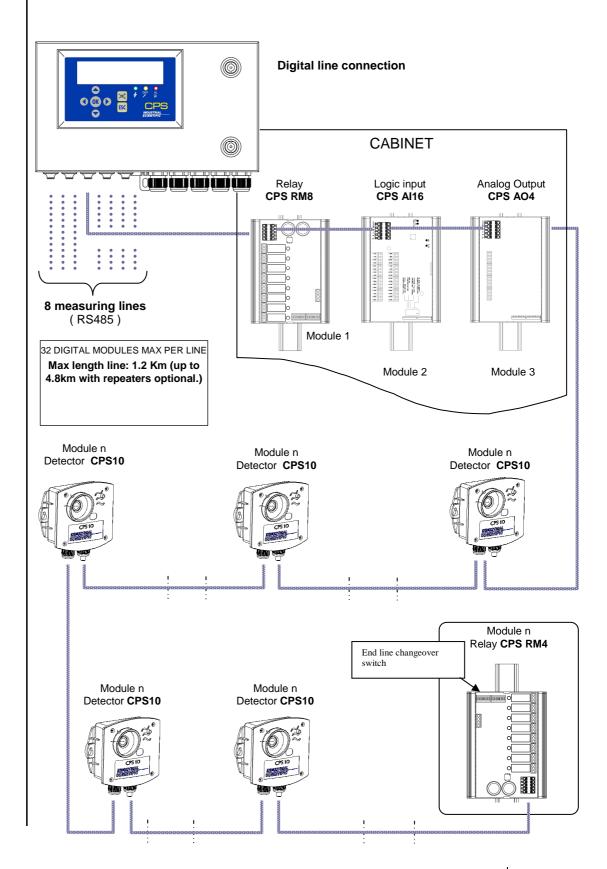
Various digital addressable modules can be positioned on the same line.



Digital linking

Modules are linked in-line via an MPI 22 or equivalent RS-485 double twisted pair cable, at least 0.22 mm² in diameter. One pair supplies power to the module, the second pair is used for the digital RS-485 link

ISC - personnel should verify that the correct cable has been used in terms of type and capacity.



The COM_CPS software application

The **COM_CPS** software application is designed to help configure the CPS central measuring controller on a PC. COM CPS software operations are addressed in a separate manual.

System and Hardware Requirements:

COM_CPS must be installed on a PC running Windows 2000 or Windows XP.

The minimum requirements to install COM_CPS are:

- Windows 98 SE, Windows NT, Windows 2000, Windows XP with 256 MB RAM, Windows VISTA.
- A CD-ROM drive
- At least 10 MB of free hard drive space
- A USB connection (cable not included) or a free RS-232 port (specific cable provided) to link the CPS central measuring controller to the PC.

Refer to the COM_CPS software instructions before installing or using the software, and before programming the central controller.

The COM_CPS software allows you to:

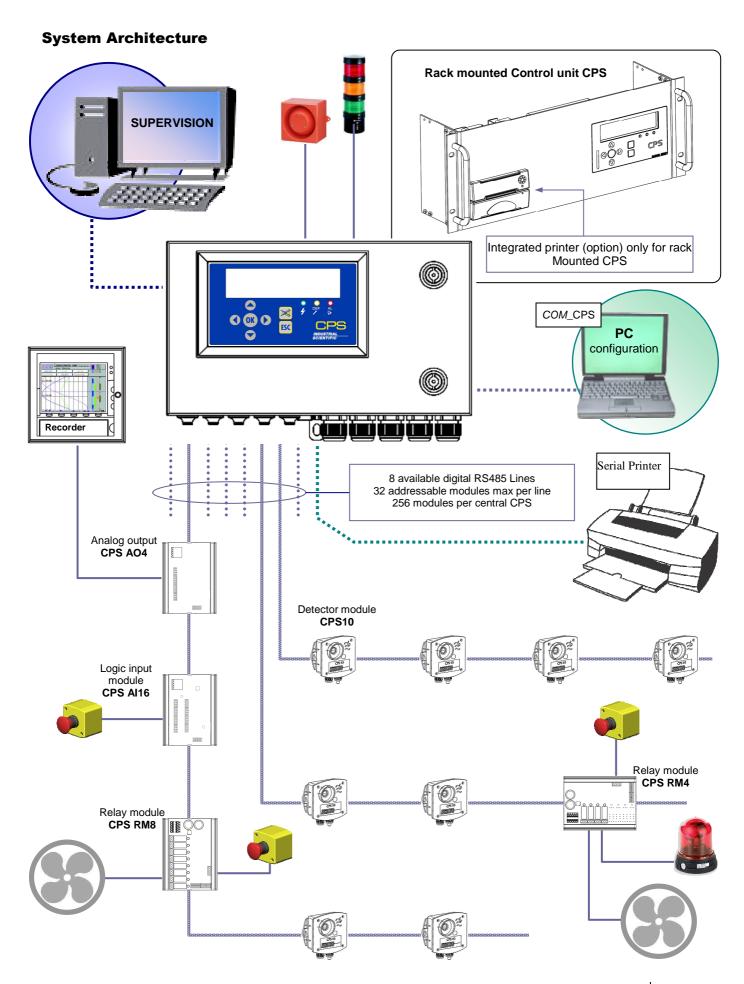
- configure one or more central controller(s) via PC;
- save settings and upload them later to the CPS central controller(s).
- view or modify central controller configuration data within the application.

The COM_CPS software can be used to modify the following main configuration settings:

- STEL and TWA calculations
- Predefined status tables printing times
- Conditions that would activate an internal buzzer
- Communication speed for the RS-485 series connection with a master device
- Settings for various sensors and alarm values
- Personalized sensor add-on options
- Delay settings
- Rising edge or falling edge triggers
- Average alarm integration time
- Verification of explosive gasses
- Creation of installation architecture: sensors/relays

COM_CPS

Whenever this sign appears in front of a chapter, the functions described in that chapter are configured with the COM_CPS software.



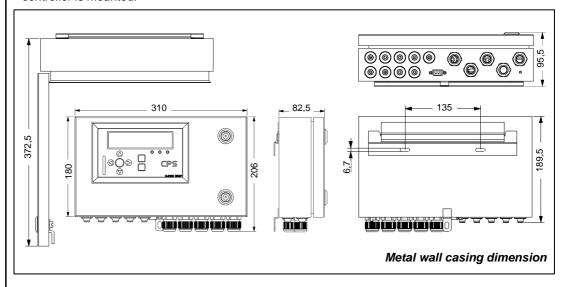
Chapter 2 Assembly / Installation

Installation of the CPS central controller

The CPS central controller should be installed in a dry, climate-controlled area protected from explosive gases and dust. Ideally, the station should be located in a secure, accessible location under surveillance (security office, control room, equipment room ...).

Mounting the metal wall casing

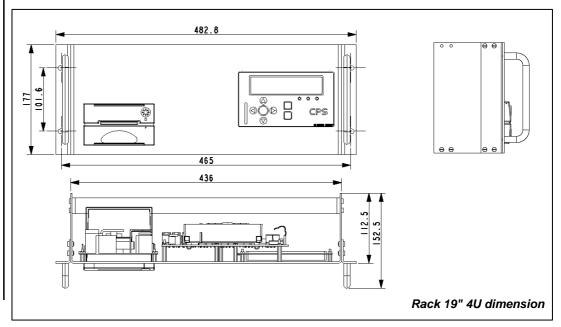
For the wall-mounted CPS in a metal case: The central controller cover opens at a 90° angle to the left. Make sure to leave adequate space to completely open the cover once the central controller is mounted.



Mounting the 19" 4U rack

The 19" 4U rack version CPS can be integrated into a rack or a 19" cabinet:

Mount the display at eye level for optimal viewing. Leave at least ½ U (22 mm) on all sides of the central controller to ensure proper ventilation.



Installing digital modules

Mounting the CPS 10 sensor module

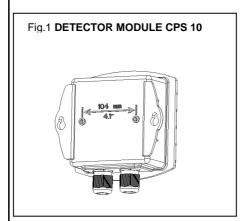
Mount the sensor modules on a flat surface using two screws (Fig. 1).

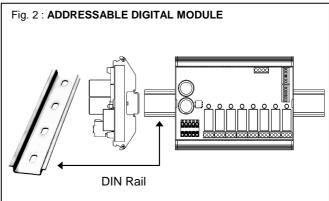
The modules should be placed in an accessible area, so that maintenance and inspection operations can be conducted as easily and as safely as possible. Nothing in the area should prevent the sensors from obtaining measurements of the ambient environment.

When mounting the sensor module on a vertical surface, position the cable glands on the underside of the module to ensure proper calibration.

Mounting the other modules

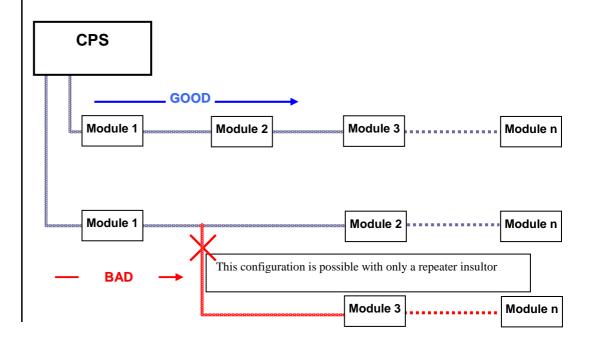
The other modules (relay, logic input, analog output) should be mounted on a DIN rail inside of a cabinet or an electric box. (Fig. 2).





Connection of modules in a line

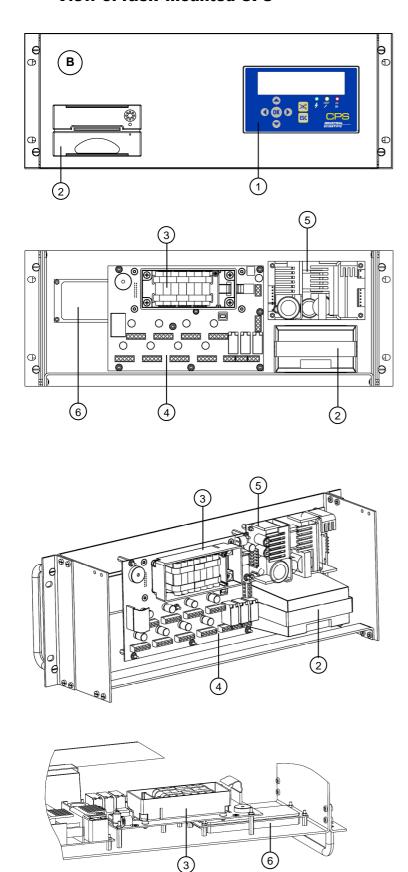
i IMPORTANT: All modules in a line should be wired in-line from the central controller, not in a hub and spoke model.

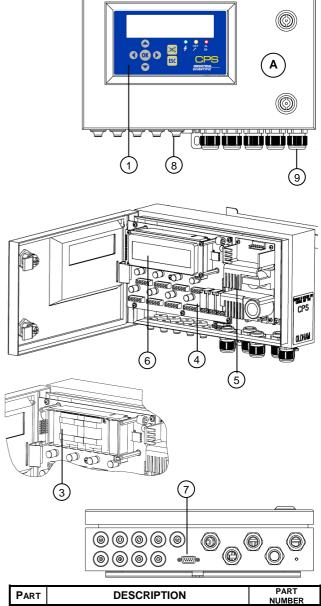


Chapter 3 The CPS Central Measuring Controller

View of rack-mounted CPS

View of wall-mounted CPS





PART	DESCRIPTION	PART NUMBER
Α	CPS WALL CASING	6 514 868
В	CPS RACK 19" 4U	6 514 869
1	CPS FRONT PANEL	6 122 477
2	AP1200 PRINTER	6 114 632
3	BATTERY PACK (OPTIONAL)	6 311 098
4	CPS MOTHERBOARD	6 451 596
5	24V 60W POWER SUPPLY BOARD	6 111 308
6	6 CPS CENTRAL CONTROLLER DISPLAY	
7	RS232 SUB D9 CONNECTOR	6 116 263
8	M16 GROMMET: D5 to D7mm	6 131 166
9	M20 CABLE GLANDS : D6 to D12 mm M20 PE PLASTIC SCREW	6 143 504 6 143 529

Central controller electrical connections

Electrical connections are wired through the central controller MOTHERBOARD and the power supply 24V. For the CPS central controller (wall-mounted version), you must open the casing door to access the electrical panel.

Electrical connections must be done by a qualified professional. Observe all current Directives, notably the European Low Voltage Directive. Customers in France must observe standard NF C 15-100.



WARNING

Contact with voltage may result in serious injury or death.

Install all equipment and complete all wiring work before turning on the power.



WARNING

Improper installation can result in incorrect gas level readings or system failure.

Carefully follow all instructions to ensure proper system operation.

Main power supply

Test the current and voltage running through a network before making any connections. Never connect the device without first disconnecting the power supply. The central controller does not have an on/off switch.

Protect the central controller from upstream current with a 4A bipolar differential circuit breaker with a type D response curve. This circuit breaker must be included in the electrical installation of the building and must be placed near of the device and must be available for the operator. On the circuit breaker will be indicated that it is the circuit breaker of the device.

Main power supply 100-240VCA: connector terminals L, N, and PE of the power supply 24V (Fig 3) for wall-mounted version or see connector picture 4 for rack version..

Pre-cabled wires are used to connect to the 24 VDC power supply module. The transformer output connector is also hardwired to link to the 24 VDC central controller connector and to the (optional) integrated printer for the rack-mounted version.

Grounding the central controller

The central controller is intended for use in areas that meet the Class II requirements for overvoltage and degree of pollution as per EN IEC 60947-1. In order to comply with the standard, the internal ground terminal *must* be grounded (Fig 3).

Digital lines

The various digital modules are connected with "Bus" connectors (Fig. 5). Recommended cable: RS-485: 2 shielded twisted pairs, 120 Ω .

One pair is used to power the module, and the other is used for communication. The cable shield or tress should be connected to the terminal: \bot

1 Data wires and the schield wires should be cut as short as possible.

Internal relay dry contacts

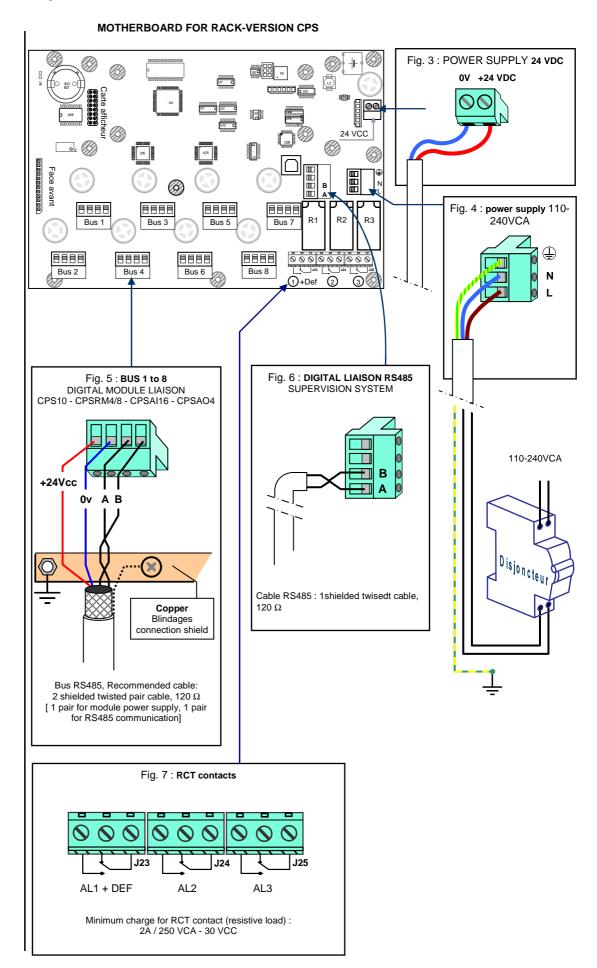
The RCT dry contacts for the 3 internal relays R1, R2, and R3 are available on the CPS central controller motherboard on connectors J23, J24, and J25 (Fig. 7). Working load: 2 A at 250 VAC, 24 VCC.

Associated alarm type: R1 (alarm/fault), R2 (alarm), R3 (alarm).

RS-485 serial link out

Recommended cable:

RS-485 cable: 1 shielded twisted pair, 120 Ω . (Fig. 6).



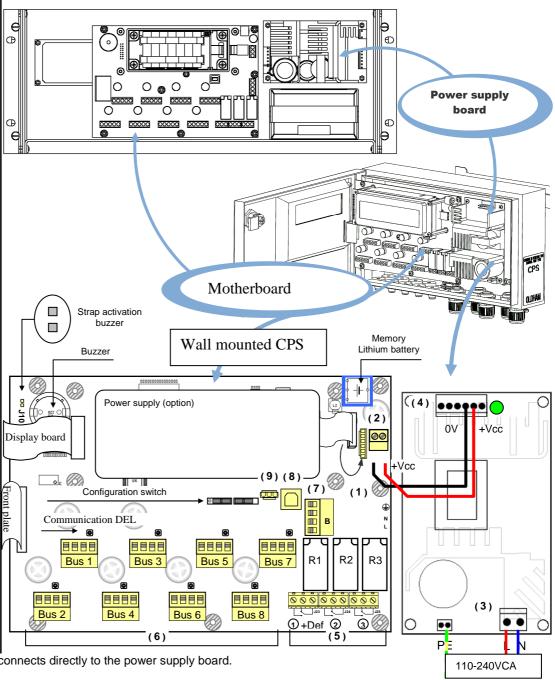
Overview of the Motherboard

Part **Connector function**

- 110-240VCA main power supply (rack (1) version)
- (2) 24 VDC external power supply connection
- (3) 110-240VCA power supply for (wallmount) power supply module
- (4) 24 VDC power supply output for power supply module motherboard + integrated printer (rackversion option) power
- (5) Internal contact relay outputs (RTC) dry contacts, potential free

Part **Connector function**

- Digital addressable modules (6) 8 line connectors for connecting digital modules (CPS10 - CPSRM - CPSDI16 - CPSAO4)
- (7) RS-485 digital output links to a supervision system
- USB serial interface (8) (PC/COM_CPS connection for configuration)
- RS-232 serial interface link (9) PC/COM CPS connection for configuration. External serial printer connection
- R1, R2, R3: central station shared internal relays

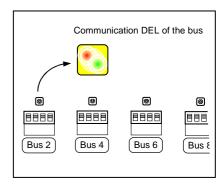


The wall-mounted version connects directly to the power supply board.

Inspecting the digital buses

Bicolor (red/green) LEDs located above each line start, on the motherboard, allows for inspection of the bus links as follows:

LED appearance	Status
Red + Green LEDs lit (LEDs blink rapidly, almost imperceptibly) Orange in appearance	Normal operation. Red LED→ question Green LED ← response
Red LED blinks once per second (green LED is off) Red in appearance	Communication fault. Missing or faulting module.
Irregular blinking	Poor communication quality
Both LEDs off.	No active modules

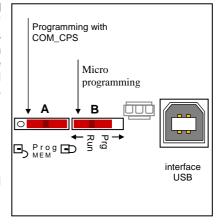


Mini-switches

Mini switch A allows the CPS controller to download and read the user program. When the switch is in the "MEM" position (open padlock), the user program memory is accessible and the message "switch open" is displayed on screen. The CPS central controller waits to download the program from the *COM_CPS* software. The CPS central controller goes into "shut-down" mode when mini switch A is in the "MEM" position.

When the COM_CPS software programming is complete, the mini switch should be flipped back to the "Prog" position (closed padlock), and the central controller should be rebooted to initialize all of the newly loaded settings.

Mini switch B only used for the central controller's internal microprocessor. It should always be in the "Run" position.



Internal relay and buzzer

The CPS central controller is equipped with 3 internal **relays** [R1, R2, R3] and a shared **Buzzer**. The operating settings for the relays and the buzzer can be set with the *COM_CPS* software (see table below).

The internal buzzer is activated when a specific program-defined event occurs (fault or alarm). All lines share relays R1, R2, and R3.

The Buzzer's pitch will vary according to the alarm threshold. Alarms 1 and 2 have the same frequency. Alarms 3 and 4 have a different pitch, allowing the operator to distinguish between alarm levels.

The Buzzer can be disconnected by removing the "Buzzer activation strap" (J10) located on the motherboard next to the Buzzer (cf: Overview of the Motherboard).

Function / Component	Relay R1	Relay R2	Relay R3	Buzzer
AL 1	Х	Х	X	X
AL 2	X	Х	X	X
AL 3	X	Х	X	Х
AL 4	Х	Х	Х	Х
Module error		Х	Х	Х
System fault*		Х	Х	Х
Out of Range and Fault	Х	Х	Х	Х
Positive security		Х	Х	

^{*: (}System fault) alarm is triggered if there is a communication fault betweenmodules, a short-circuit in a power supply line, or a module inversion.

X: Function can be activated or deactivated

■: Default configuration setting, cannot be changed by user.

USB / RS-232 serial connectors

The CPS central controller is equipped with a serial port which are used to:

- download the user software (see COM_CPS instructions);
- program the integrated micro application according to the position of mini switches on the board (factory setting).
- **1** The serial port has 2 interfaces: USB and RS-232. Only one can be used at a time.

The settings for the central controller can be modified after the program has been created. (Use either the USB or RS-232 adapter to connect the PC to the CPS central controller.

(See Chapter 7 - Program transfer).

USB Interface (1)

Use a USB cable to connect the PC to the CPS central controller running the COM_CPS application.

The USB interface emulates a serial port and is preferable to an RS-232 serial connection.

The corresponding USB driver must be installed before the PC is connected to the central measuring station (see *COM_CPS* instructions).

SUB-D 9 RS-232 Interface (2)

Use a cross-over RS-232 serial cable to load the user software.

RS-232 cable series reference number: **6 116 026**

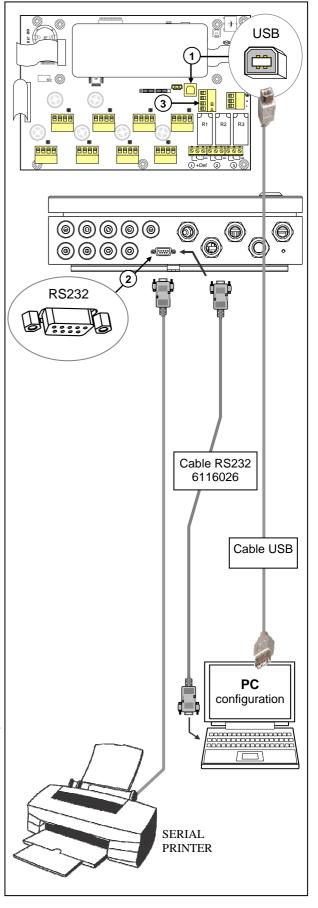
A serial printer can be permanently connected.

This would allow you to load the software via the USB interface without disconnecting the printer.

RS-485 serial connection (3)

The RS-485 serial port (3) is reserved for the supervision system and is composed of an RS-485 interface using JBUS/MODBUS protocol.

A table containing all of the important information pertaining to the central controller can be found in the corresponding annex of Chapter 8.



Printer (Optional feature)

Connection: Central controller RS-232 interface via an RS-232 serial cable.

Communication settings: 19200 Bd, 8 bit, no parity.

Event printing "on the fly."

<u>Status table printing</u> (choice of four printing schedules). For example: average readings over 20 minutes, 1 hour, or 8 hours, summary of alarm and relay statuses.

"Out of paper" functionality: no data is lost when the printer runs out of paper. Once more paper has been loaded, printing will resume where it left off.

Data flow is managed as follows: XON/XOFF Protocol

The printer is ON

The central controller sends data to the printer on start-up. If the printer's power supply fails or if the RS-232 cable is disconnected, data sent from the central controller will be lost.

In the event that the RS-232 cable becomes disconnected, it may be necessary to turn the printer off and on again to reinitiate data transfer.

The printer is OFF

No data is delivered to the printer. The central controller stops sending data when the printer signals the CPS central controller that it is no longer available (Buffer is full, out of paper, or printing stopped with the ON/OFF button).

The central controller will reinitiate data transfer once the printer signals that it is available (empty buffer, or signal through the printer's ON/OFF button or online button).

The front panel circuit

The central controller front panel circuit is equipped with:

1 LCD display: backlit, 2 lines by 32 characters and a pictogram line for viewing sensor readings and the zone in question, various test point data, settings, events, etc.



3 lights on the front panel of the central controller (green for power, yellow for errors, and red for exceeding thresholds) serve as constant system status indicators.

7 keys to select on-screen information and/or validate certain operations via menus. The menus are available in English, French, German, Spanish and Dutch.

Display Screen

No alarms or errors



Icon associated with one or more alarm icons indicates (by blinking) that the associated alarm is an averaged alarm.



SOLID = instantaneous alarm 1 BLINKING = averaged alarm 1 (takes priority over solid state)



SOLID = instantaneous alarm 2 BLINKING = averaged alarm 2 (takes priority over solid state)



SOLID = instantaneous alarm 3 BLINKING = averaged alarm 3 (takes priority over solid state)



SOLID = instantaneous alarm 4 BLINKING = averaged alarm 4 (takes priority over solid state)



SOLID = stable signal in hysteresis interval (calculated over 1 minute)



SOLID = signal increased in relation to the minute before BLINKING = Exceeding the scale (takes priority over solid state)



SOLID = signal decreased in relation to the minute before BLINKING = Negative fault (takes priority over solid state)



SOLID = buzzer on



SOLID = calibration underway



SOLID = LS (low speed) relay control active



SOLID = HS (high speed) relay control active



SOLID = Error



SOLID = mains power supply OK BLINKING = battery or mains power supply problem

Kevs



Keys primarily used to modify values (ex: line number)



Keys primarily used to navigate menus or to change variable current (ex: go from line number to sensor number)



Key used to validate a menu or an input that would alter system operation. (ex: activation of a relay)



Key used to return to a previous menu screen or to cancel a selected value before it has been validated.



Key used to acknowledge a locked alarm (programmed for manual acknowledgement) or to dismiss a buzzer relay after its holding time, even if an alarm is still active.

Lights



Green LED: power supply status indicator SOLID = OK

BLINKING = power supply problem (no power to main or problem with the battery pack)

Orange LED: indicates the presence of one or more faults.

Red LED: signals the presence of one or more alarms.

COM_CPS

Alarm thresholds

Six alarm thresholds can be programmed and adjusted for each sensor:

Alarm 1, Alarm 2, Alarm 3, Alarm 4, Out of Range and Fault.

Alarms 1 - 4 can be:

- Instantaneous:
- delayed (0 to 3,600 seconds);
- averaged (period of 1 to 480 minutes).

This makes it possible to calculate STEL and TWA values.

So, for example, you could choose to activate Alarm 1 if the average calculated levels over a period of 8 consecutive hours exceeded 50 ppm, and Alarm 2 if average levels over a period of 10 minutes exceeded 100 ppm, and Alarm 3 if the instantaneous reading exceeded 200 ppm.

Averaged alarms are only triggered at the end of a complete time interval.

If the line or the detector module stops, average value calculations are halted and will only begin again once the line or the detector module has been reactivated.

Both the instantaneous and averaged alarms can be set to trigger on an increasing value (rising edge) or on a decreasing value (falling edge).

- Rising edge: alarm is activated when levels increase. Use this option for sensors measuring Explo, CO, H₂S, etc.
- **Falling edge**: alarm is activated when levels decrease. Use this option for O₂ sensors, for example.

Out of Range alarm: can activate an alarm, a relay, or an LED.

"Verification" option: this option is activated for explosive gases. When a "verification" alarm occurs, the level displayed will be frozen at the maximum value until it is acknowledged (manually or automatically) and on the condition that the gas levels have fallen under the alarm threshold.

Example of ventilator command functionality for CO/NO detection

Alarm threshold	CO (ppm)	NO (ppm)	RESPONSE
Alarm 1	50	25	Ventilators start on low speed
Alarm 2	100	50	Ventilators go to high speed
Alarm 3	150	75	Max speed ventilation + alarm lights in the surveillance area
Alarm 4	200	100	Visual & audible alarms + restricted area access + evacuation orders for individuals in the area

COM_CPS

Alarm acknowledgement

Alarms can be rearmed in two ways:



Manual acknowledgement: the audible alarm can only be dismissed after the "Acknowledge" button on the CPS central measuring controller has been pushed; or

Automatic acknowledgement: the audible alarm will be automatically dismissed once the alarm condition has ended.

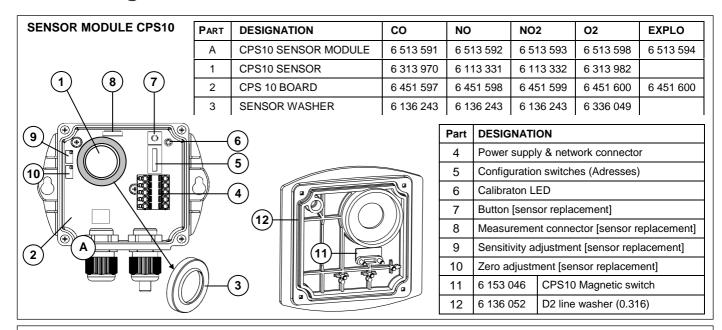
If an alarm is triggered, a corresponding message will appear on the screen, an audible alarm (BUZZER) is activated, and the red LED on the front panel is illuminated.

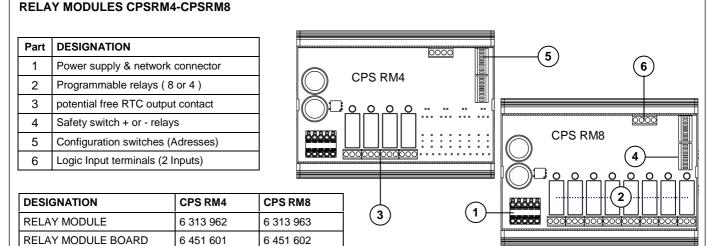
Touching the "Acknowledge" button once will remove the message from the screen and will turn off the BUZZER.

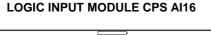
Touching the "Acknowledge" button a second time will re-arm the programmed alarms. These alarms will not turn off until the concentration of gas falls below the threshold.

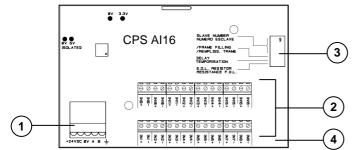
Chapter 4 Digital Modules

View of Digital Modules



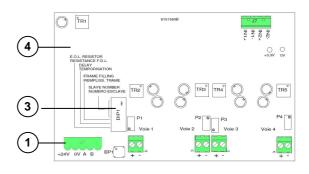






Part	DESIGNATION
1	Power supply & network connector
2	Logic input terminal (16 Inputs)
3	Configuration switches (Adresses)
4	Module board

ANALOG OUTPUT MODULE CPS A04



DESIGNATION	CPS AI16	CPS AO4
MODULE	6 313 964	6 313 980
MODULE BOARD	6 451 603	6 451 614

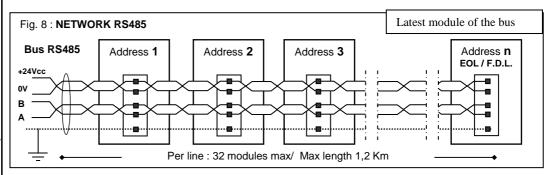
Connecting Digital Modules

General topology of the RS-485 network

Modules are connected in "parallel" in the RS-485 network, comprised of a 1 twisted pair cable for signals, 1 or more pairs to supply power to the modules, and 1 shield wire.

A 120 Ω end of line resistor (**EOL RESISTOR**) should be placed at the last module in the line, at the end of the bus (see Chapter 6 - End of Line Resistor).

The modules are equipped with a double connector, which can be split to easily connect conductors and also allows you to isolate the module while maintaining line continuity.



Wiring the digital network

The sensor module has two cable glands. One connects to the input wire, and the other connects to the output wire which is routed to the next module.

The modules should be wired with RS-485 shielded twisted pair cable, with a normal resistance of 120 Ω , of at least 0.22mm² in diameter. +24VDC, 0V A and B terminals are linked to +24VDC, OV terminals A and B in other modules in the line, and then linked to the connector corresponding to the central controller. The cable shield should be connected to a ground terminal marked with the following symbol: (Fig.9).

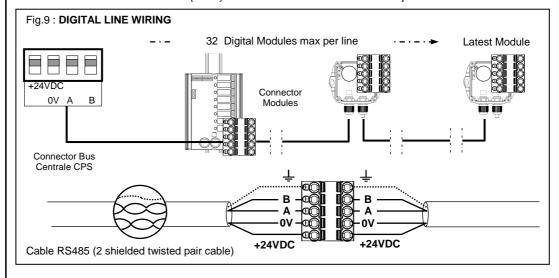
WARNING

An improper installation can cause incorrect gas level readings or system failure.

Do not run cable near equipment such as motors, transformers, or any lines generating a large magnetic field.

Always check to ensure that the cables are completely separated from other circuits.

1 Do not leave any stripped wire ends exposed. To guard against electromagnetic disturbances, the data cables and the screen (tress) cables should be cut as short as possible



Configuring the communication settings

Slave address

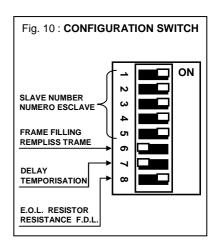
All modules in a line should be identified with a unique slave number. Switches 1-5 on the **configuration Switches** unit (Fig. 10) contained in each module, allow you to set a binary numerical address (1...32).

Possible combinations are listed in the address table below.

Notes: The physical address of a module (1...32) should be identical to the address recorded in the central controller configuration program with *COM_CPS*.

When replacing a module, set the configuration switches in the new module to the same position as those of the module being replaced.

1 Switches 6 (FRAME FILLING) and 7 (DELAY) should be in the OFF position (unused options).



End of line resistor

The last module in each line should be equipped with an end of line resistor.).

1 This switch should be in the OFF position for all other modules in the line.

Address Table

SS	SWITCHES						
Slave Address	ON = 1; OFF = 0						
Ac	1	2	3	4	5		
1	1	0	0	0	0		
2	0	1	0	0	0		
3	1	1	0	0	0		
4	0	0	1	0	0		
5	1	0	1	0	0		
6	0	1	1	0	0		
7	1	1	1	0	0		
8	0	0	0	1	0		
9	1	0	0	1	0		
10	0	1	0	1	0		
11	1	1	0	1	0		
12	0	0	1	1	0		
13	1	0	1	1	0		
14	0	1	1	1	0		
15	1	1	1	1	0		
16	0	0	0	0	1		

SS	SWITCHES							
Slave ADdress	ON = 1; OFF = 0							
AE	1	2	3	4	5			
17	1	0	0	0	1			
18	0	1	0	0	1			
19	1	1	0	0	1			
20	0	0	1	0	1			
21	1	0	1	0	1			
22	0	1	1	0	1			
23	1	1	1	0	1			
24	0	0	0	1	1			
25	1	0	0	1	1			
26	0	1	0	1	1			
27	1	1	0	1	1			
28	0	0	1	1	1			
29	1	0	1	1	1			
30	0	1	1	1	1			
31	1	1	1	1	1			
32	0	0	0	0	0			

CPS 10 Detector Module

The CPS central controller accepts 10 types (or 10 different configurations) of sensors. The type of sensor used in the module depends on the gas being monitored. Electrochemical sensors are used to measure CO, NO, NO₂, for example, while catalytic sensors measure gases such as GPL, CH₄, and H₂).

Available Detector Types

Sensor			Measurement		Sensor life expectancy
Carbon monoxide	CO	:	0 300	ppm	36 months
Nitric oxide	NO	:	0 100	ppm	24 months
Nitrogen dioxide	NO_2	:	0 30.0	ppm	24 months
Methane	CH₄	:	0 100	% LEL	48 months
Liquefied petroleum	LPG	:	0 100	% LEL	48 months
Hydrogen	H_2	:	0 100	% LEL	48 months
Oxygen	O_2	:	0 30.0	% v/v	12 months

Sensor module fault

In the event of a sensor module fault, gas levels are no longer taken into account, and all alarms are cancelled, except for the negative threshold (or fault) which is activated. Average values are no longer taken into consideration and the calculation of average values is paused.

If a sensor faults, it can be replaced while the central controller is still running (hot swap) without replacing the detector.

Detector settings

The following settings apply to each type of detector:

- The abbreviated name to be displayed on the central controller: NO, CO, CO₂...
- The name of the gas: Carbon monoxide, Nitric oxide, Oxygen, Methane ...
- **Unit:** ppm, LEL, %v/v ...
- Range with display format: 100, 10.0, 1.00, ...
- Actionable thresholds:
 - o 4 instantaneous thresholds: 0-100% measuring range,
 - 4 averaged thresholds: 0-100% measuring range, (time interval programmable from 1 to 480 minutes).

If the operating time is inferior to the averaging time interval, the averaging time interval is ignored.

An instantaneous threshold is associated with an averaged threshold to generate an alarm. These two thresholds can be set to trigger on the rising edge (increasing alarm) or the falling edge (decreasing alarm).

Alarm delays (0s to 60 min):

Each of the 4 alarm thresholds can be delayed. If gas levels are in excess of an alarm threshold for an amount of time inferior to the programmed delay, the alarm will not activate.

The alarms can be acknowledged automatically once the alarm is turned off, or manually when the gas levels are once again under the threshold.

■ Fault thresholds:

- o "underscale" negative signal (exceeding the lower threshold): -10% of the range.
- o "SUP" out of range (exceeding the upper threshold): +120% of the range.
- o "Verification" for all explosive gas sensors, in case an LEL threshold is passed, the SUP alarm remains on even after levels fall under the threshold. The fault alarm is also triggered.

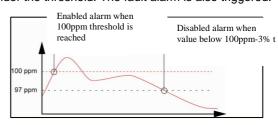
Hysteresis:

Max. 1% of range. Default value = 0%.

Example (see opposite page):

Measurement range = 300 ppm; Alarm = 100 ppm; Hysteresis (1% of range) = 3 ppm

Level at which alarm can be dismissed = 97



External relay module

The relay module is available in two versions: CPS RM4 (with 4 relays) and CPS RM8 (with 8 relays). It also has two logic inputs (LI) which can be activated.

In maximum configuration, the CPS can manage 256 relays (ex: 32 modules with 8 relays each). For more information about the logic inputs: see: Logic inputs module.

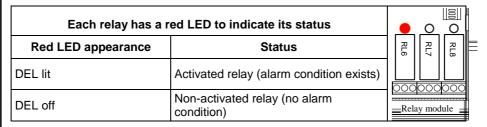
The relays are individually programmable. The operation of each relay depends on its configuration and its function.

Each of the 6 sensor alarms [AL1 - AL2 - AL3 - AL4 - Out of Range - Fault] can control one or more of the 256 relays. Several events can be linked to one relay.

In case of a module relay fault, all relays of this module are restarted.

The CPS central controller will change the relay status unless they belong to a different module type. Restarting will resolve the problem.

Relay status lights



"Positive/negative" relay security

In addition to switches of CONFIGURATION, RELAY MODULES INCLUD SWITHCHES OF POISITVE AND NEGATIVE SECURITY CONFIGURATION. Flip the switch to **ON (positive security)** or **OFF (negative security)** as desired. Each switch acts on its corresponding relay (switch $1 \rightarrow$ relay RL1, switch $2 \rightarrow$ relay RL2, etc.). (Fig. 11).

Note: Only switches 1-4 are active in the CPSRM4 module. Fig. 11: « POSITIVE / NEGATIVE » RELAY SECURITY CONFIGURATION (LI) SWITCH Relay module **CPS RM8** CPS RM4 8 Red DEL: Relay status [1à4] CPS RM8 [1 à 8 ON = SECU + 0 ယ RL2 RL5 RL6 RL3RL4 RL_8 RL7 R1 G 0 **Output contact Relay** Logic input (LI) Minimum charge for contacts N 핍 핍 2A / 250 VAC (Load charge) ᆸ

COM_CPS

Relay configuration

"Normal" relays

The relay is activated when an alarm occurs and is deactivated when the alarm condition ends.

The variables acting on a relay in alarm status are:

- Alarm delay
- Automatic / Manual acknowledgement
- Forced state change via the CPS menu
- Forced state change via a logic input command

"Buzzer" relays

The "Buzzer" relay is used to control an audible alarm.

It can be re-armed with the [Acknowledge] key on the central controller, even if the alarm condition has not changed.

The occurrence of a new alarm will reactivate the relay and reset the delays.

The "Buzzer" relay can be automatically dismissed before the end of the alarm with a 15 to 900 second delay (standard setting for "Buzzer" relays) or manually, even if the alarm condition has not changed. It can be configured with a minimum operating time of 1 sec. to 5 min.

The variables acting on a relay after an alarm has occurred are:

- Alarm delay
- Automatic / Manual acknowledgement
- Forced state change via the CPS menu
- Forced state change via a logic input command

Alarm and/or "Buzzer" relay delays

Alarm delays		Relay delays
Instantaneous		"Buzzer modes"
Instantaneous Alarms	Averaged Alarms	Min. activation time: 0 300 seconds
1 3600 seconds	1 480 minutes	Acknowledgement time: 15 900 seconds
Standard settings for each sensor type		Standard settings for all "Buzzer relays"

"LS/HS" Relays

Low speed (LS) relays and high speed (HS) relays are always used together, allowing you to control a parking facility ventilation system at two speeds.

LS (low speed): The relays are designed to control slow ventilator speed (star-triangle configuration for a two-speed ventilator).

HS (high speed): The relays are designed to control high speed ventilator speed (star-triangle configuration for a two-speed ventilator).

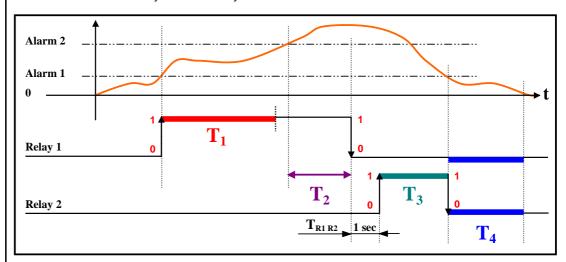
The working logic of the relays defined hereafter, takes into consideration the start-up and shut-down intervals during which very high levels of current may occur, capable of damaging motor windings if phases occur in the incorrect sequence.

"LS / HS" Operation

Requirements: Alarm level 1 < Alarm level 2

The LS relay is activated by Alarm 1

The HS relay is activated by Alarm 2



Phases		Action operation	Default Delay*
T ₁	Min. duration LS operation Adjustment(s): [1 32767]	Minimum duration, in seconds, during which the ventilator operates at low speed	5 min.
T ₂	HS operation delay Adjustment(s): [2 32767]	Minimum duration for Alarm 2, after which the ventilator switches to high speed	15 min.
T _{R1}	LS/HS transition time 1 second (cannot be changed)	Transition time between Relay 1 and Relay 2 is 1 second (standardized throughout the central controller)	1 sec.
T ₃	Min. duration HS operation Adjustment(s): [1 32767]	Minimum duration, in seconds, for the ventilator to operate at high speed. HS relay deactivated if Alarm 1 condition ends	10 min.
T ₄	LS-HS stop delay Adjustment(s): [1 32767]	Duration, in seconds, after low or high speed ventilator operation has been stopped, before the ventilator can be restarted at low speed.	10 min.

Time values T_1 , T_2 , T_3 and T_4 can be modified. When the "Sensor simulation" menu is used (see the chapter on the maintenance menu/simulation on page 43) the times are decreased, by default, to 12 seconds, 24 seconds, 36 seconds, and 24 seconds, respectively.

Note: An underscale alarm (= fault) activating a LS or HS relay will force the relay into HS position (with respect to the defined time).

"Forced ventilation" function

This is a forced relay state change via the CPS menu. This function allows you to block or release the HS (high speed) command at specified times.

Forced relay state change via a logic input command

In both cases the response is immediate and priority safety settings are maintained: HS takes precedence over LS, and both relays are shut-down if there are contradicting signals.

Logic Input Module

COM CPS

This module contains 16 logic inputs, linking priority commands, such as fire extinguishers directly to the central controller.

A maximum of 224 total logic inputs across all modules can be activated.

Example 1: 112 modules having 8 relays each, with activated inputs.

Example 2: 7 modules with 16 logic inputs with activated inputs.

Each input can override all other commands to activate or block up to 256 relays.

Priority inputs.

Two levels of input priority can be managed on each module with the COM_CPS software.

Priority inputs have control of the other inputs (all of the non-priority inputs are "blocked" when a priority input is activated).

In the event that two different inputs of the same priority level send contradicting orders, the relay is shut-down.

In the event of a fault, the inputs are set to zero.

CPS Al16

CP

COM_CPS

Analog Outputs Module

This module is comprised of 4 opto-isolated 4-20 mA analog outputs which can be individually activated or deactivated.

Activated: the output analog signal (4-20 mA) varies, according to the input

Deactivated: the analog output signal will be frozen at 0mA, regardless of the input signal.

Several events can be linked to one output. In this case, the largest analog value will be recopied onto the analog output.

The output module also has two logic inputs (LI), identical to those on the "Logic input" module.

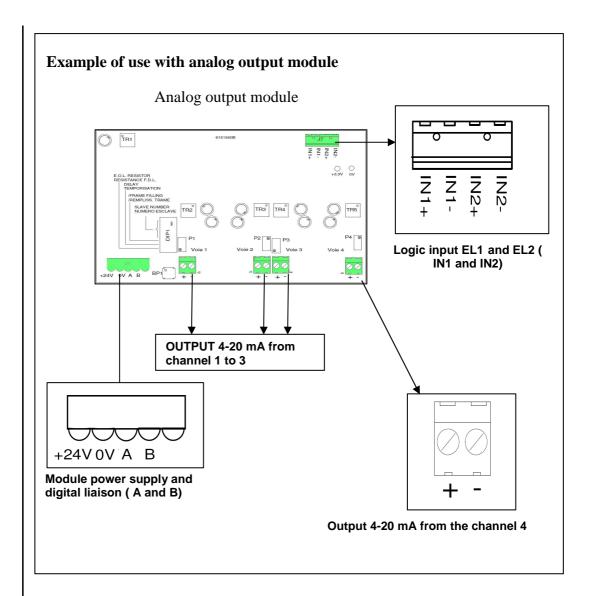
A "slave address" for the module can be set with the "DIP" switch (DIP1).

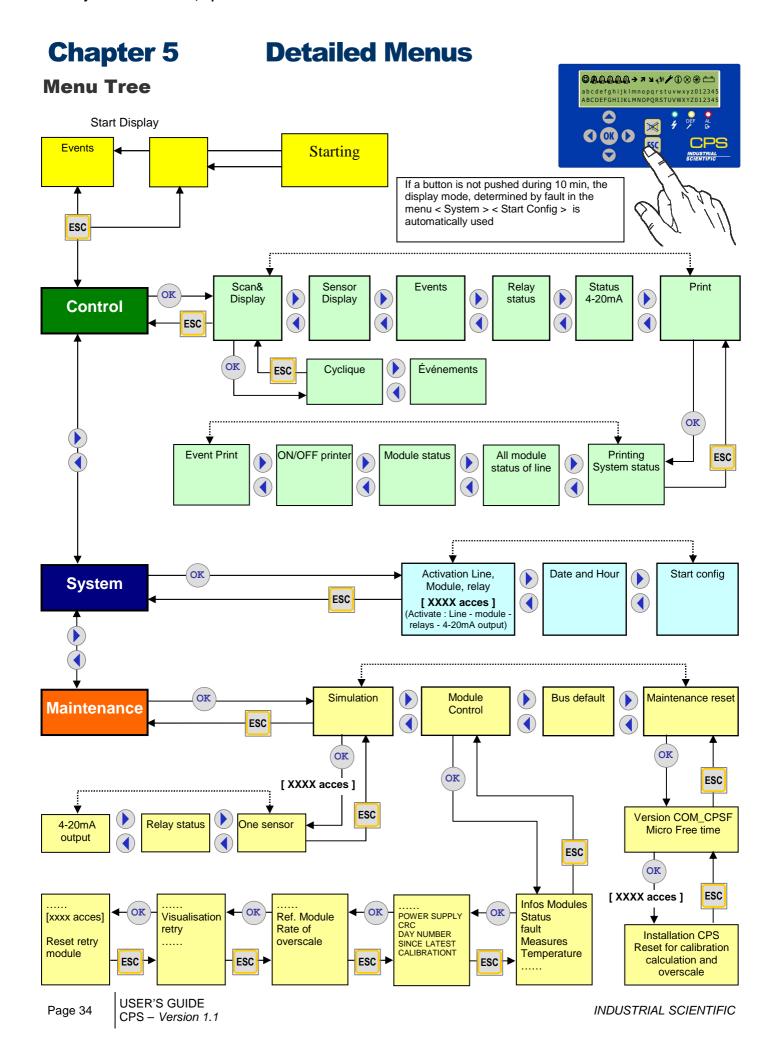
An analog output OFF command from the central controller corresponds to 4 mA.

An analog output ON command from the central controller corresponds to 20 mA.

Connections:

Analog output module





Start-up Phase

No faults or alarms are processed during the first minute after start-up. During this phase, the central controller runs a Checksum test (1), a RAM test (2), a line start-up (3) and a module mapping test with a program stored in its memory.

Voltage builds progressively in the lines. Progress bars show the overall progress for line power-up.

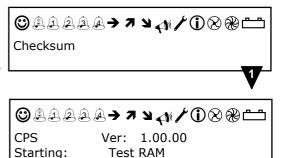
Only the power-up of activated lines is shown (identified by a diamond " ♦ " during the initial power-up phase, and by a black square " ■ " at the end.)

An exclamation point "!" indicates a short-circuit line fault. The line can be reactivated through the menu system.

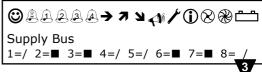
Next, a sensor stabilization phase occurs (4) during which time, the alarms are deactivated.

An inspection phase immediately follows in order to verify that the configuration program set with the *COM_CPS* software correctly maps to the modules installed and activated.

If no errors are found, the program runs normally. If errors are detected, the modules in question will be flagged as faulting.







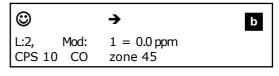


After the start-up phase, the screen will display information pertaining to the selected mode: events (a) or cyclic (b). The central controller begins to process data coming in from the various modules

In cyclic display mode, when no alarms are triggered the levels from each sensor are displayed on the first line of the display screen.

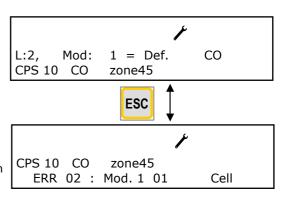
In case of a power outage, the program configuration will be saved. When the controller is turned on, the last program installed by *COM_CPS* will be loaded.





If a sensor faults, the message "Def" will replace the reading value. If the power supply is interrupted within a line, the two points in front of that line will blink. Identify the problem by touching the [ESC] key to display the error message.

If the gas level exceeds a high or low threshold, "Ovs" will appear on the display screen where the value for that sensor would normally appear. This message will display simultaneously with a blinking arrow (pointing up or down, depending on the situation).



Control Menu

Normal Display

Alarm pictograms will appear and disappear in along with the alarm conditions detected by a given sensor. The display shows gas level readings, which may not always be identical to the status of a relay. Under normal conditions, alarm pictograms reflect relay status.

Example: LS and HS relays are configured to run on a delayed trigger. Pictograms do not take this delay interval into consideration. So it is possible that the LS or HS relay is on, while the alarm pictogram does not display on screen, due to the alarm delay.

Cyclical display

This menu allows you to view all of the activated sensors on screen, at a display rate of one sensor every two seconds.

Event display

This menu allows you to view the status of all sensors in alarm mode, faulting, or in calibration, at a rate of one sensor every two seconds.

Sensor Display

This menu allows you to freeze the display on a specific sensor by selecting the line and the module number (The program automatically selects active sensor modules).

Touching the [**OK**] key once will bring up the sensor name, the abbreviated gas name, the gas level and unit of measure (ppm, % LEL, \$v/v).

If the sensor is faulting, "Def" will display in place of the level reading.

Select the line or the sensor (if appliable) using the [\P] [\blacktriangleright] (horizontal) keys.

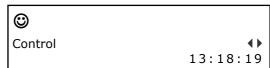
Select the line number or the sensor number (if appliable) using the [$^{\blacktriangle}$] [\checkmark] (vertical) keys.

Press [OK] to select the sensor.

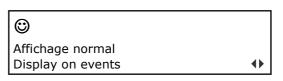
Press [OK] a second time to display both the gas reading level and the 4 averaged readings if average readings were activated. If averaging was not activated, < *** > will display on screen.

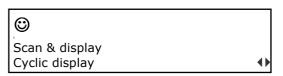
If a communication fault occurs, the value will be replaced by < *** > and the averages will stop on the last calculated value.

For all other faults, the gas level will be displayed in order to help the user identify the problem.

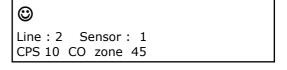


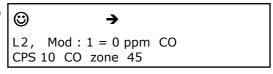


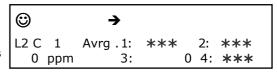


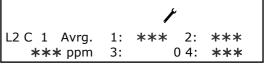












```
L2 C 1 Avrg. 1: *** 2: ***
-37 ppm 3: -1 2 4: ***
```

Events

This menu can be used to search through a history of the most recent 1,200 events. A record of these events can be printed. State changes are recorded in the history.

If Alarm 1 ends and Alarm 2 is triggered, AL2 ON will be recorded.

Examples

- (a) The shut-down of a line causes the shut-down of alarms and relays for that line.
- (b) The "fault" alarm is triggered for module 3, line 1.

Other examples:

Module 2, line 8 turned on

30/06/06 (day/month/year) 14:40:36 L:8, Mod:02 Module ON

Alarm 2 triggered

30/06/06 14:49:37 L:8, Mod:02 Alarm 2, OFF \Rightarrow ON

State change for Relay 2 (command relay)

Control
Events

(a)

30/06/06 14:49:37 L-8 Mod-29

Relay 2 Normal ON

<u>Conditions for Alarm 2 end</u>
30/06/06 14:51:03 L:8, Mod:02

Alarm 2. ON ⇒ OFF

Acknowledgement action

25/ 06/ 07 19:06:02 Line 2 OFF

30/06/06 14:55:21

ACKNOWL

State change for Relay 2 (relay shut-down)

30/06/06 14:55:21 Alarme

Relay 2 Normal OFF

Relay Status

This menu displays the status of a relay in a given module. Increments for the preceding and following modules in the line are automatically calculated.

Display the status for the selected relay by pressing the [OK] button. This screen will show the module, its mode of operation (Normal, Buzzer, LS, HS,...) and its status (ON, OFF).



0

Line: 2 MoDule 1 Relay Module Level-1

(a): (LS / HS) - Delays

(a): (Buzzer Relay) - Acknowledgement time

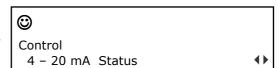
(b): (Buzzer Relay) - Min. activation



4-20 mA Output Status

This menu displays the outputs for the selected module. The value is displayed in mA.

Multiple inputs can be linked to one output. In this case, the largest analog value will be recopied onto the analog output.



Activated analog output: the 4-20 mA output signal varies according to the input.

Deactivated analog output: the 4-20 mA output signal will be frozen at 0mA, regardless of the input signal. The output current for each channel will vary between 0 and 24.5 mA.

Printing

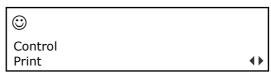
"System status" Report

This menu is used to initiate the printing of system status reports. The second part indicates the fault status for all of the modules in each line. Each hexadecimal number corresponds to a module, with Module 1 being on the left, and Module 32 on the right.



0 = OK

- 1 = Communication error
- 2 = Module recognition error
- 4 = Fault triggered by a module fault word.
- X = (no programmed module)



If the system detects an abnormality in either the name or the range of a gas, the letter N will blink on the screen

"Status for all line modules" Report

Sensor module: the printed reports will contain both the reading and the averages if averages are activated.

Relay module: the printed reports will contain the status of each relay and of each relay's logic inputs.

Logic inputs module: the printed reports will contain the status of all logic inputs.

"Module status" Report

Prints the status of every module in the selected line. See previous paragraph.

"Printer On/Off" Report

Use the [riangleq] , [riangleq] keys to activate or deactivate the printer.

When the printer is activated, the **COM_CPS** cannot be used to for reading or configuration. The configuration mini-switch (A) must be placed in the open padlock position to enable communication between the serial port and the **COM_CPS** software (cf "Programming mini-switches").

"Event" Report

This feature allows you to print all of the most recent events stored in memory (up to 1,200).

Calibration Report: The calibration data for a sensor is only printed at the end of the calibration process. The record will consist of a title, the line number and module number and 6 readings if a complete calibration has take place:

Calibration1Sensor 4 01 COXo1 = 00004Zero value before starting procedureXo2 = 00000Zero valueXo3 = 00000Zero value after procedureXf1 = 00095Value of the concentration of calibration gasXf2 = 00100Value of the response to the gasXf3 = 00100Value of the reading at the end of the procedure

Acces code

An access code is required to access certain menus. The access code is made up of 4 hexadecimal numbers. If the wrong code is entered three consecutive times, the code will be deactivated until all menus have been exited or until after 10 minutes of inactivity. The **COM_CPS** software can be used to modify the access code.

The default access code is: 1 0 0 0

System Menu

Line, Module, Relay Action

Enter the access code by using the $[\land] [\lor]$ and $[\land] [\lor]$ keys.

Line activation

The selected line is displayed along with its number and name.

To go to a different line, use the

[♠] [▼]. Change the status by pressing the [**OK**] key, and then pressing the [◀] [▶] keys, followed by [**OK**].

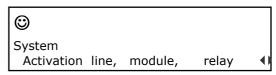
If the line is shut-down, the line number will flash intermittently with a cross sign. If the module does not correspond with the CPS central controller COM_CPS-created program, its status is reported as faulting.

Notes: If the line is shut down by the COM_CPS software, it is impossible to turn it on.

A line is fully activated approximately 5 seconds after start-up.

A thermal fuse protects the line's power supply from short-circuits. Should a short-circuit occur, a fault word will appear in the menu and an error message will be recorded in the event log. After the short-circuit, the line must be reactivated via the menu.



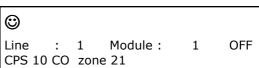












Relay activation

Use the same "Relay Status" menu to select a relay. After pressing [**OK**] to select the relay, you have three options:

< Normal > = Relay functions normally (triggered by alarms)

< ON > = Relay in forced operation (can only be shut-down by a logic input)
< ON > = Relay in forced shut-down (can only be turned on by a logic input)

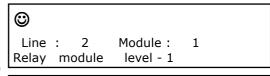
Special case: LS and HS relays

For safety reasons, deactivating a LS or HS relay via the CPS central controller shuts down of the two relays and restarts their timing devices.

If a logic input or a command from the CPS central controller activates a LS or HS relay, the relay will be activated. The relay's activation time is set to the maximum value. In other words, the forced relay shut down ends when logic inputs no longer command the relay or after the end of an alarm condition which could control the relay.

Similarly, if an alarm triggers a HS relay, a LS relay cannot be activated.

②Activate Relay ◆▶





The forced activation of a HS relay takes priority over scheduled HS freezes.

Activating analog outputs

Choose the 4-20 mA output for the selected module. Pressing [OK] will force a start-up or shut-down for the 4-20 mA output.

- The shut-down freezes the output at 4 mA.
- The start-up freezes the output at 20 mA.

Output 4 - 20 mA

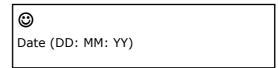
Date and Time

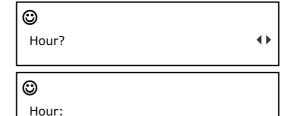
△ Changing the time settings will reinitialize LS and HS delays!

Example: If the HS relay is activated and the time is changed, the HS relay will stop so that the LS relay can operate according to the predetermined delays.









09:36

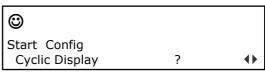
Start-up Configuration

This menu is used to select which menu will display by default upon start-up and after 10 minutes of keyboard inactivity.

The two menu options are:

Cyclical Display and Event Display.







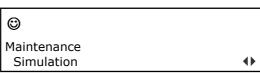
Maintenance Menu

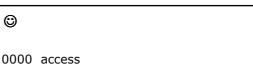
Simulation

This menu is used to simulate the alarms for a particular sensor module or to temporarily activate one or more relays (or outputs). After exiting the simulation menu, the sensors and relays (excluding LS and HS relays) revert to their prior state.

Enter the access code by using the $[^{\land}] [\checkmark]$ and $[\checkmark] [\blacktriangleright]$ keys.







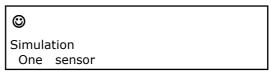
Sensor simulation

Select the sensor module you wish to test. Next, select the delay between each of the alarms to be activated (1-59 sec.). Validate your selections by pressing [**OK**].

The central controller will increase reading levels until they exceed the thresholds for all activated alarms in ascending order +/- hysteresis. During the simulation, the theoretical values are displayed on screen.

During this phase, the other sensors are shut down. However, forced-state lines, modules and relays remain active.









Relay Status Simulation

Select the relay module for the relay you wish to test, then the relay you wish to activate.

Use the same "Relay Status" menu to select a relay. After pressing

[**OK**] to select the relay, you have three options:

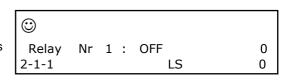
< Normal > = Relay functions normally (triggered by alarms)

< ON > = Relay in forced operation
(can only be shut down by a logic input)
< OFF > = Relay in forced shut-down
(can only be shut down by a logic input)

After exiting this menu, the relay will revert to its original state.





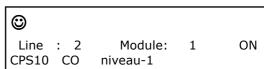


Analog Output Simulation

Module Verification

Inspection of all of the parameters relating to a module with a *communication fault*.





E = Status word

D = Fault word

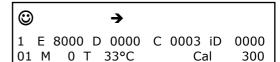
C = Start-up config. word

M = Level for sensor modules or State for logic inputs

T = Temperature

Cal (Value) = Concentration of gas used for calibration

ID = Module fault



Displays useful variables and operating time according to the module type:

(Value) = line voltage

R = Relay status (hexadecimal)

(**Value**) J = Number of days since last calibration.

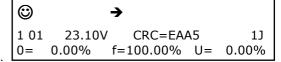
0 = X0 for sensor modules.

f = Xf for sensor modules.

U = Wear rate for sensor modules.

CRC = (Cyclic Redundancy Check)

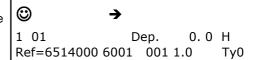
Software version for the module program.



② →2 01 22.37V CRC=404CR=00

Dep. (value) H = Time (in hours) during which the sensor exceeded the scale.

Ref: (Value) = Sensor reference.

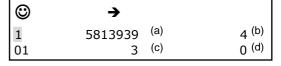


Retry: (plural form, *retries*) – attempt(s) at retransmission. Used to control the quality of communication with the modules.

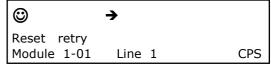
(a): represents successful transmission attempts. This number increases continually and should be as large as possible.

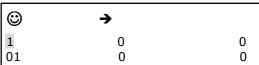
(b), (c), (d): represents next 3 successive retransmission attempts, if necessary, following a failed attempt. In the event that the 1st attempt (1) fails, a 2nd attempt (b) will occur, then a 3rd (c), and 4th (d). The number and the level of saved attempts is indicative of the transmission quality. A large number, on level 3 or 4 is due to poor transmission.

Reinitialize "retries" by selecting the "Reset retry" menu.



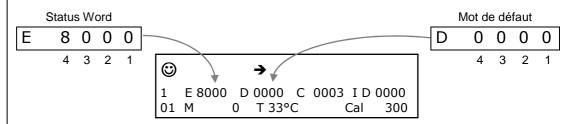






Any module fault generates an event, which is identified by a number (hexadecimal coding) corresponding to the fault type. The number at the end of the second line displays the module error.

The [◀] [▶] keys can be used to change the scroll mode: in normal mode, all events saved to memory are displayed; in default mode, only the faults saved to memory are displayed.



Fault word

4	3	2	1
1 = Def Flash	1 = Def Temp. Min	1 = Def Zero calibration	1 = Def ROM main memory
2 = Def sensor	2 = Def Temp. Max	2 = Def Sens. calibration	2 = Def RAM
4 = Low line power	4 = Def Meas. Min	4 = Def Zero Sensor replacement	4 = Def Battery
8 = high line power	8 = Def Meas. Max	8 = Def Sensitivity. Sensor replacement	8 = module parameter does not correspond to the module card

Sample fault word: 00A0 = Def Sens. calibration + Déf Sensitivity. Sensor replacement (A = 10 in hexadecimal = 8 + 2)

Status word

4	3	2 *	1
1 = BitEtatLiss	1 = BitEtatChg	1 = BitEtat0	1 = BitMod0
2 = BitJbFill	2 = BitEtatPar	2 = BitEtat1	2 = BitMod1
4 = BitJbDelay	4 = BitJbWait	4 = BitEtat2	4 = BitMod2
8 = BitEtatCell **	8 = BitJbCar	8 = BitEtat3	8 = BitMod3

**: only for sensor module (indicates presence of a sensor)

2 *	Status
0 (EtatMes)	Normal measure
BitEtat0 (EtatStab)	Stabilization
BitEtat1(EtatZInit)	Zero init
BitEtat0 + BitEtat1 (EtatStab)	Zero Stabilization
BitEtat2 (EtatZVal)	Zero validation
BitEtat0 + BitEtat2 (EtatSWait)	Sensitivity waiting
BitEtat1 + BitEtat2 (EtatSInit)	Sensitivity init
BitEtat0 + BitEtat1 + BitEtat3 (EtatSStab)	Sensitivity stabilization
BitEtat3 (EtatSVal)	Sensitivity validation
BitEtat0 + BitEtat3 (EtatChg)	Button replace pushed

М	odule Designation	Туре
1	Sensor CO	0
2	sensorNO	1
3	Sensor NO ₂	2
4	Sensor EXPLO	3
5	Sensor O ₂	4
6	Free	5
7	Free	6
8	Other	7
9	4 relay mod	8
10	8 relay module	9
11	Free	А
12	Free	В
13	4ana output mod	С
14	16 log input mod	D
15	Analog input mod	Е
16	Free	F

Bus Faults

This menu displays the faults from all modules in a line. Each hexadecimal number corresponds to a module, with Module 1 being on the left, and Module 32 on the right.

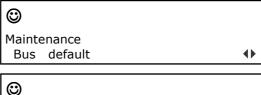
0 = OK

1 = Communication error

2 = Module recognition error

4 = Fault triggered by a module fault word.

X = module missing or unrecognized due to a conflict with another module



Module 32

Module 1

Line: 1 Module: 1 = OK

Line: 1 Module: 2 = module recognition error Line: 1 Module: 3 = communication error

Reset maintenance

1 Reserved for ISC- maintenance personnel only.



CPS / COM_CPS Version – Available memory level

Displays the CPS central controller version as well as the COM_CPS programming software version.

Displays the microcontroller availability (time) rate (in %). This value will vary somewhat in relation to the program but can detect if a microprocessor is being overtaxed.

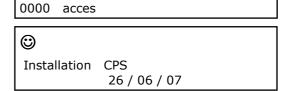


Enter the access code by using the [$^{\blacktriangle}$] [$_{\blacktriangledown}$] and [$^{\blacktriangleleft}$] [$^{\blacktriangleright}$] keys.

Next, press the [OK] key to reinitialize all counters to zero and to refresh the date.

CPS Installation

This menu is used to zero the following two settings across all modules: Last zero date



Operating Time

Each module logs its operation time in days. For the sensors, this time is equal to the time since the last calibration or the last zero.

 \odot

Exceeding the scale

Each sensor logs the amount of time that levels exceed the scale in seconds. Go to the "Module Verification" menu to see this time.

Chapter 6 Maintenance

Program transfer

This chapter describes the transfer of data from the COM_CPS application to the CPS, and vice versa (see the COM_CPS user's guide). After launching the software, you will see a welcome window.

PC → CPS transfer

Once the program has been created, the central controller should receive new settings...

Step 1: establish a physical connection

- Use either the USB or RS-232 adapter to connect the PC to the CPS central measuring controller.
- 2) Ensure that the CPS central measuring controller is connected to a power source.
- 3) On the central controller: flip the programming switch to the "MEM" position. The message "Switch open Program..." will appear on the display screen. Communication with the central controller is authorized during this phase..

Step 2: link configuration

- 1) In the menu bar, select [Communication > Port].
- 2) Select the port [COM x] to use on the PC.

Note: communication speed is selected automatically.

Step 3: data transfer

- In the menu bar, select [Transfer > from PC to CPS]. The message "Flip switch to MEM position in order to reprogram the central controller" refers to the <MEM> position on the CPS central controller commutator before starting the transfer procedClick [OK] once verification has ended.
- 2) During the transfer, a progress bar will indicate transfer progress.
- Once the transfer is complete, the message "Operation complete" will appear on screen. Click [OK]. The configuration program has been transferred from the PC to the CPS central controller.
- 4) On the central controller: The message "Switch open Complete" will appear on the display screen. Flip the programming switch to the "Prog" position.
- The central controller will perform a "Start-up" procedure.

CPS → **PC** transfer

Step 1: establish a connection

- 1) Use either the USB or RS-232 adapter to connect the PC to the CPS central controller.
- Ensure that the CPS central measuring controller is connected to a power source.
- 4) On the central controller: flip the programming switch to the "MEM" position. The message "Switch open Program..." will appear on the display screen. Communication with the central controller is authorized during this phase.
 - Or, use the "Control" menu to set the printer to "OFF."

Step 2: link configuration

- In the menu bar, select [Communication > Port].
- 2) Select the port [COM x] to use on the PC.

Note: communication speed is selected automatically.

Step 3: data transfer

- 1) In the menu bar, select [Transfer > from CPS to PC].
- 2) The message, "Do you want to read the CPS central controller configuration?" will appear onscreen. Click [OK]. If the message, "Check port configuration and ensure printer set to OFF position and try again" appears, verify that the CPS printer is in the OFF position.
- Select the folder where you want to download the file, and create a file name (a default name is suggested).
- 4) During the transfer, a progress bar will indicate transfer progress.
- 5) Once the transfer is complete, the message "Operation complete" will appear on screen. Click [OK]. The data has been transferred from the CPS central controller to the PC.
- 6) On the central controller: The message "Switch open Complete" will appear on the display screen. Flip the programming switch to the "Prog" position.
- 7) The central controller will perform a "Start-up" procedure.

Error messages

Error messages will appear in the following scenarios:

ERR 01: Module fault relating to the program.

The test runs systematically on start-up and periodically when a module is activated by the menu if the module does not correspond to the loaded program. The error remains until the problem is corrected or until the module is shut down.

ERR 02: Fault word reading for a module. Name displayed on the 1st line of the screen.

ERR 04: Power line error.

ERR 08: 12C (real-time clock) or EEPROM error.

ERR 10: Module communication error.

ERR 20: Problem originating at printer. Printer shut-down or lack of paper.

Checksum error

When the central controller starts up, checksum values appear briefly on screen after the display test. The value calculated by the central controller is displayed on the first line, and the checksum calculated by the PC with the *COM_CPS* software is displayed on the 2nd line.

If these two values are different, this screen will remain on the display screen, indicating that there is a problem (example: depleted battery.) The user program protection switch must be flipped, and a new *COM_CPS* program must be transferred.

Flip the switch back into the "closed padlock" position before restarting the central controller.

Example of an error

Operation before event

CPS Analysis 21:04
Parking Charles de Gaulle

Technical alarm triggered (fault). Buzzer engaged (if activated), Front panel yellow LED illuminated. Two pictograms appear: the blinking "maintenance key" and the "siren."

CPS Analysis 21:04
Parking Charles de Gaulle

Action on the front panel "acknowl" button. Audible alarm (Buzzer) is off.

"Siren" pictogram disappears.

"Maintenance key" pictogram remains on screen. Front panel yellow LED illuminated. CPS Analysis 21:07 Parking Charles de Gaulle

Action on the "acknowl" button.
Direct access to the "ERRORS" data page.
ERR 11 = ERR 10 + ERR 1

Communication fault for Module 1, Line 2.
Check the line and/or the module. The fault will disappear when the problem is resolved.

Relay module level-1 ERR11 : Com. 2 01

If multiple errors occur, all of the error codes will be displayed one after another. The faulting modules for each error will be displayed one at a time by their line number and module number.

For all faults except for communication faults, the gas level will be displayed in order to help the user identify the problem.

Sensor CO 1, level-1 ERR01 : Type 2 01 Meas=x.x

Testing and calibration of stable installations

Warning: The setting of this section are reserved for authorized persons formed because they might call into question the reliability of detection.

The site responsible is required to establish security procedures on its site. Industrial Scientific may be not responsible for their implementation.

Gas detectors are above all safety instruments. In consideration of this, *Industrial Scientific Corporation* recommends regular planned testing of fixed gas detection installations.

A functional test involves injecting a sufficient concentration of gas at the sensor level to trigger preset alarms. This test does not replace a full sensor calibration under any circumstances.

Industrial Scientific also recommends fully calibrating detectors with a known and certified concentration of gas every 3 months.* The frequency of calibrations will depend on the application for which the detector is used (exposure to high concentrations of gas, frequent exposure to concentrations of gas, the type of technology used in the sensor, environmental conditions...).

If a gas detector does not respond correctly to a gas test, full calibration with a known gas is mandatory. These recommendations are consistent with applicable industry safety protocols and with the standards and directives relative to the safety of industrial sites. Furthermore, *Industrial Scientific* is not responsible for any procedures implemented at a site.

- . Gas concentration which must be used during manual or semi automatic calibration
- CPS10 explo = 2,5% CH4/air
- CPS10 CO = 100ppm
- CPS10 **NO** = 50ppm
- CPS10 NO₂ = 10ppm

Sensor replacement

Sensors should be replaced as a part of regular preventative maintenance or following a failed calibration test.

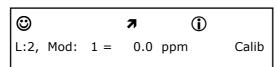
After replacing a sensor, a calibration test must be conducted (see the chapter on semi-automatic calibration).

To replace a sensor:

- Remove the sensor cover.
- Hold down the sensor replacement button (1) for 5 seconds, until the solid green LED (2) is on.
- Release the button.
- Replace the sensor and conduct a calibration test (mandatory) according to the semi-automatic procedure.

On the central controller, the "maintenance key" pictogram indicates that the sensor has been replaced. The key will remain on screen until the sensor has been calibrated or until the sensor's power supply fails.

The wear settings for the sensor are initialized upon calibration



INDUSTRIAL SCIENTIFIC

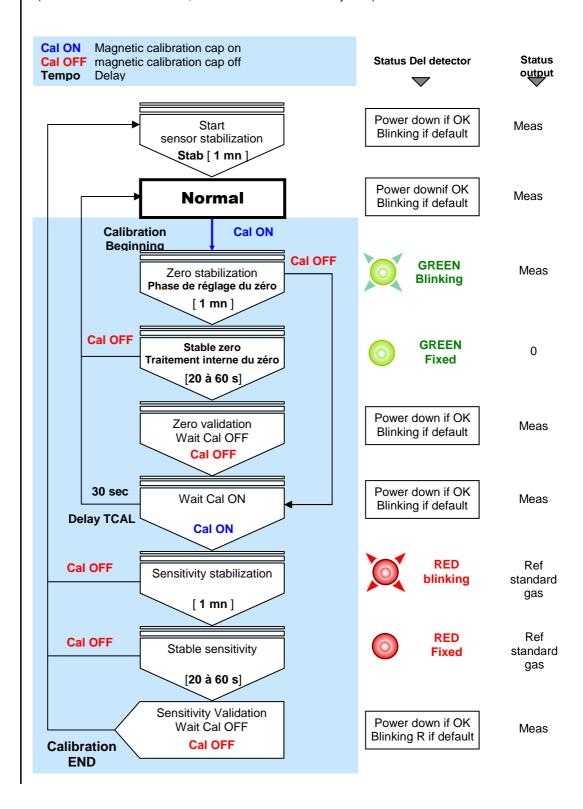
Semi-automatic calibration

During a sensor module calibration, the central controller blocks the alarms from the module in question and displays a maintenance key on the screen. Up to 10 sensors can be calibrated at the same time. The concentration level for the calibration gas is stored in the sensor's memory.

Each calibration start and stop is logged as an event.

The printer records a state after the calibration of each sensor (cf: Printing).

If the calibration is failed, the sensor is listed as faulting and an event is logged with a fault code (0010 - calibration zero fault, 0020 = calibration sensitivity fault).



Manual calibration

The calibration kit provided by ISC must be used (Ref. 6 116 291) female connector / wires / voltmeter connection files).

- Remove the sensor cover.
- Connect the cable (strand) to the circuit's male connector.

Zero adjustment

Ensure that the sensor is in clean air. If not, inject air into the sensor at a flow rate of 60 l/h, then wait for voltmeter levels to stabilize (use the gas injection device: bottle of synthetic air, calibration pipe, tube).

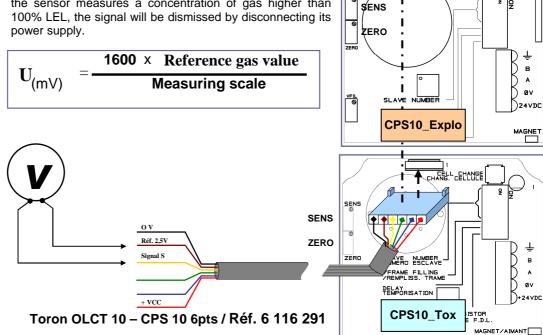
Adjust the zero with the potentiometer's "ZERO" until the voltmeter reads 0 mV.

Sensitivity adjustments

- Now inject the known gas (60 l/h) into the sensor, and wait for the voltmeter signal to stabilize.
- Adjust the sensitivity if necessary with the potentiometer "SENS" until the signal value (in mV) corresponds to the amount of reference gas used. Use the following formula to calculate the correct value for the signal.
- Stop injecting gas (remove the calibration pipe from the sensor).
- Wait for the voltmeter to "return to zero."

Version CPS 10 for explosive gas

The CPS central controller has a "verification" function: if the sensor measures a concentration of gas higher than



MAINTENANCE WIRES:

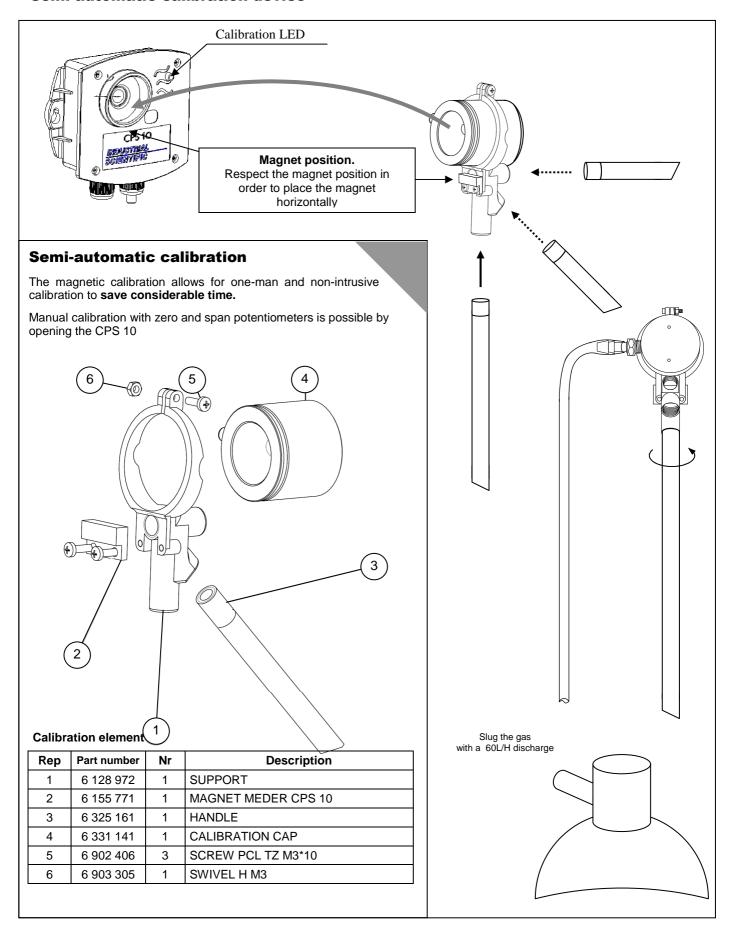
+VCC (red) = + power supply

Signal S (yellow) = signal from 0 mV to 1600 mV for zero and sensitivity measure Ref 2,5V (brown) = zero reference for signal reading from 0 mV to 1600 mV

GND (**black**) = electronic circuit ground.

무

Semi-automatic calibration device



Central controller maintenance

Do not use alcohol- or ammonia-based liquids to clean the central controller. If necessary, clean the exterior of the central controller with a damp cloth.

Lithium battery

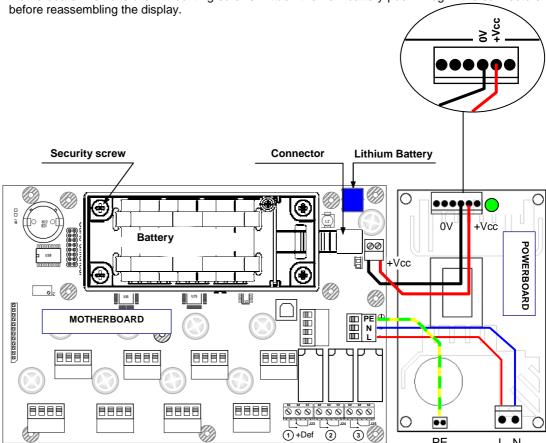
If the central controller configuration settings are lost, the lithium battery soldered to the display card must be replaced. This operation should be performed by a qualified professional.

Lithium battery characteristics: VARTA CR1/3N or equivalent.

Back-up battery pack

When the back-up battery power drops, the battery should be replaced. This operation should only be performed by a qualified professional.

The battery pack is located underneath the display screen on the wall-mounted version. Take off the display screen to access the battery pack. Unplug the connector linking the battery pack to the motherboard. Remove the 4 mounting screws. Attach the new battery pack. Plug in the connectors



Scrapping of CPS System

Concerning the conservation, of the protection and the improvement of the quality of the environment, as well as for the protection of the health of the persons and the careful and rational use of natural resources, CPS system has to be the object of a selective collection for the electronic equipments and cannot be scrapped with the normal domestic waste. The user thus has the obligation to separate the CPS system of the other waste so as to guarantee that it is recycled in a sure way at the environmental level. For more details of the existing sites of collection, contact the local administration or the distributor of this product.



Chapter 7 Technical Specifications

CDC/ matal!!	B' ' () 000 400 05
CPS w/ metal wall-mounted casing:	Dimensions (mm): 320 x 180 x 95
	Degree of protection: IP 54
Cable entries	5 M20 cable glands Diameter 5-12 mm power / local relays 9 PG9 1 D-SUB 9 Pin RS-232 cable
CPS rack version	Dimensions: Length: 19"; Height: 4 U (176 mm) IP class: IP 31
Operating conditions	
Ambient temperature:	-10℃ to 40℃
Storage temperature:	-20℃ to 85℃
Humidity:	5 to 95% noncondensing
Power supply	
Mains power supply:	Voltage: 110-240VCA
Battery back-up:	Optional – Capacity: 600 mAh
24 V Consumption:	140 mA + 12 mA per measurement line (240 mA max.)
Measuring lines	
Number:	8 RS-485 digital measuring lines
Line capacity:	32 digital CPS modules (CPS 10,CPS RM, CPS DI16, CPS AO4) ModBus Protocol
Cable type:	2 twisted pairs shielded RS-485 4Xawg22 (diameter 0.67mm) cable, 120Ω
Transmission speed:	9600 Bauds (trial with 0.35 mm²)
Module power supply:	12 to 30 VCC via the CPS central controller and if necessary via a 24VCC external additional power supply
Digital module network:	RS-485 ModBus, addresses 1 to 32, set with mini switches
Isolation:	Power supply / Digital network: 1500 V
Display	Backlit LCD display [2 lines, 32 characters per line - 1 line for pictograms - 3 electroluminescence diodes to indicate operating status: OK, Fault, Alarms]
Keyboard	Membrane keyboard, 7 intuitive keys
Local buzzer	Alarm and fault signaling
Integrated printer	Optional for rack version (no integrated printer option for the metallic wall casing)
Alarms	
Number of alarms:	6 alarms per sensor (AL1, AL2, AL3, AL4, Out of Range, Fault + Validation for Explo gas)
Programmable thresholds:	For instantaneous or averaged values, increasing or decreasing values, or for manual or automatic rearming.
3 Internal local relays	Relay: R1 (alarm/fault) – R2 (alarm) – R3 (alarm). Minimum charge for RCT contacts: 2A / 250 VAC – 30 Vcc (resistive charge) Relays settings are configured with the COM_CPS configuration software. Torque: 0.5-0.6 Nm
Centralized supervision system digital	
RS-485	ModBus Protocol (connection with a centralized supervision device)
RS-232 or USB	USB protocol priority (permanent connection to system configuration)
Approvals:	
Low Voltage Directive:	This device is in compliance with the security requirements of Directive 73/23/EEC, modified by Directive 93/68/EEC, based on standard 61010-1 and its second amendment.
Metrology:	Underground parking facilities: according to VDI 2053
EMC Electromagnetic compatibility:	according to EN 50270

CPS 10 Sensor M	odule	
Dimensions (mm):	118 x 110 x 60	Topodo
Degree of protection:	IP 54	
Cable entries:	2 M16 cable glands 4-8 mm diameter	CPS 10
Consumption:	Toxic gas sensor: 2.5 mA in normal operation Explo gas sensor: 50 mA in normal operation	Sisterior (
Status indication after calibration	Red/Green electroluminescent diode	
Calibration:	Automatic, no need to open the sensor due to a gas introduction device equipped with a magnetic switch, or with a potentiometer inside of the case.	
Sensor replacement:	Sensor replacement switch on the interior of the CPS 10 case. Detection of sensor	

CPS RM4 or RM8	Relay Module	0000
Dimensions (mm):	125 x 165 x 60	CPS RM4
Mounting:	Ratchets into DIN rail	
Number of relays:	4 relays (CPS RM4); 8 relays (CPS RM8) Contact type: RCT	50000 00000000000000000000000000000000
Minimum charge for contacts:	2 A / 250 V over resistive charge	
Connection:	Screw posts (cable: 2.5 mm² max.) Torque: 0.5-0.6 Nm	0000
Consumption:	3.5 mA in normal operation	CPS RM8
Bistable Relays. Configuration of positive or nega Relay modules have 2 logic inpu Configuration via the COM_CPS		

CPS DI16 Logic I	nputs Module	T 12
Dimensions (mm):	125 x 165 x 60	CPS DI 16
Mounting:	Ratchets into DIN rail	
Number of All or Nothing Inputs:	16	
Connection:	Screw posts (cable: 1.5 mm² max.) Torque : 0.5-0.6 Nm	* 10 8 8 1 2 1 8 1 8 1 8 1 8 1 8 1
Consumption:	2 mA in normal operation	

CPS AO4 Analog	CPS AO4 Analog Output Module					
Dimensions (mm):	125 x 165 x 60					
Mounting:	Ratchets into DIN rail	<u>_</u>	CPS AO 4			
Number of analog outputs:	4-20 mA output, max. resistance 500 Ω Isolation galvanique individuelle + 2 entrées logiques		G G G G G G G G G G G G G G G G G G G			
Connection:	Screw posts (cable: 1.5 mm² max.) Torque : 0.5-0.6 Nm					
Consumption under 24V at module input	I< 5 mA if the 4 channels are shut down I< 36 mA if only one channel is activated I<130 mA if all 4 channels are activated					

Chapter 8 Annexes

JBUS/MODBUS Protocol

Nota: Relays and Inputs are numbered, from 1 to 256 and from 1 to 64 in order to optimize the occupation memory in the CPS. JBUS Transfer Table

Classification is automatically made by the COMCPS in the ascending order of the relays then modules then Ines.

dem for logic input

		:																		
Acces In read	d only by bit;	Acces in read only by bit; Function (1; 2)				Byte1							Byte2							
						7 118	9118	9 118	† 11€	2.118 2.118	1 116	0 11/9	7 118	9 118	9118	tr HE	E 11/8	Z 118	1 118	0 115
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15	∃000				2 bytes	18,MI 32, 3	.8,M 31	6Z 08 30 28	82 KS 28 Z8	.M.18.N	MLB,W 26	1.8.M 25	L8,M 24	78.M Z3	Z ZZ	L8,M L	L8,ML8, 20 19	И	18,M L8	L8,M 17
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17	0011	Aarm 2 Status of each detector module	sctor module	line, Module	2 bytes	L1, L M32 I	L1, L7 M31 M	L1, L1 M30 M	L1, L1, M29 M28	. L1, 8 M27	L1, M26	L1, M25	L1, M24	L1, MZ3	L1, L MZZ N	L1, L M21 N	L1, L1 M20 M	L1, L1 M19 M	L1, L1 M18 M	L1, M17
						╚	H	Н	Н	Н	Ц	Ц			Н	Н	H	Н	Н	П
33	1200	Aarm 3 Status of each detector mo	ector module	ldem		Ħ	H	Н	Н	Н	Н	Ц			Н	H	H	Н	Н	П
69	1600	Alarm 4 Status of each detector module	ector module	ldem				H	H	H	L				Г	Н	H	H	H	
99	1400	Alarm overscale. Status of each del	each detector module	Idem			H	Н	Н	Н	Ц				Н	Н	H	Н	Н	П
81	0051	Aarm fault Status of each detector	detector module	Idem			Н	Н	Н	Н	Ц				Н	H	Н	Н	Н	П
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elans 49-56

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Page 58 CPS – Version 1.1

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30540	774C	latest calibration	The 1	Module 28	Word	2 bytes (16 bits not signed)	
30641	774D	latest calibration	lhe 1	Module 29	Word	2 bytes (16 bits not signed)	
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30643	774F	latest calibration	Le 1	Wodule 31	Word	2 bytes (16 bits not staned)	
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36807	8FC7	event N+1199			ļ	Module number	No event
36808	8FC8	event N+1199			\mid	Edra Information	Extra Information
36810	SFCA	Pointer on the last printed le	¥	(Modulo 4)	Word		
36811	8FCB	Text M 80 byte text	đ				
36891	9018	80 byte	đ				
36971	8906	Text M + 2 80 bite text	ţ.		l		
37051	SORR	80 hybri	+				
		l					

						Swied (Swiez
						plus.
	Sing					21 118 21 118 21 118 21 118 21 118 21 118 21 118 21 118 21 118
40001	9C41	Detector measures				
40001	9C41		1 81	Wodule 1	П	2 bytes (16 bits not signed)
40002	9C42		9	Module 2	T) Julies
40003	9043	Ť	T	MODINE 3	Word	2 pytes (16 bits not signed) 5 bytes (46 bits not signed)
40009	9C45	Instantaneous measure Instantaneous measure	2 2	Module 5	T	
		١			T	
40028	9050	l	lne 1	Wodule 28	Word	2 bytes (16 bits not signed)
40029	9050	Instantaneous measure III		Wodule 29	Γ	2 bytes (16 bits not signed)
40030	9CSE			Module 30		2 bytes (16 bits not signed)
40031	9C5F		lhe 1	Module 31		2 bytes (16 bits not signed)
40032	9080			Wodule 32	П	2 bytes (16 bits not signed)
40033	9C61			Module 1	Word	2 bytes (16 bits not signed)
40034	3C62			Module 2	Word	2 bytes (16 bits not signed)
					Г	
40065	9081	Instantaneous measure IIIn	E 3	Wodule 1	Word	2 bytes (16 bits not signed)
		ľ				
40097	9CA1	Instantaneous measure IIIn	Te 4	Wodule 1	Word	2 bytes (16 bits not signed)
40129	9003	rill entsteam superchaten	5 65	Modula 1	Word	2 hydes (16 hits not stoned)
		١			Г	
40161	9CE1	Instantanecus measure	9 6	Module 1	Word	2 bytes (16 bits not signed)
40493	anot	all seem a constraint	7 00	Storting 1	Word	2 hides (18 hits not signed)
	-]		200	
40226	9D21	Instantaneous measure In	8 8	Module 1	Word	2 bytes (16 bits not signed)
03000	option	ľ		8 01100	T	Shakes (48 bite rod elemod)
4000	9040	III Ballaleous III easnie	0	module 32	WORL	Z Dytes (To Dis Fot Signed)
40257	9D41	-				
						2111 2111 2111 2111 2111 3111 3111 3111
40057	9041	14-20mA Outputs Value (1000 = 1	mA)			
40257	9D41	Output4-20mA Value 0t	utput1		Word	2 bytes (18 bits not signed)
40258	9D42		Output2		Word	2 bytes (16 bits not signed)
40259	9D43		utput3		Word	(16 bits not
40260	9D44	٥	utput4		٦	2 bytes (16 bits not signed)
40261	9D45	Output4-20mA Value ou	utputs		٦	_
40262	9D46	٥	utbut8			2 bytes (16 bits not signed)
40263	9D47	٥	ulput7		T	2 bytes (16 bits not signed)
4 0264	9D48	٥	utputs		7	2 bytes (16 bits not signed)
40265	9049	Output4-20mA Value ou	elindir		7	2 bytes (16 bits not signed)
40266	9D4A	8	othrito		7) yes
40267	9D4B	Output4-20mA Value ou	IIIDUIT1	† 	T	2 bytes (16 bits not signed)
4 0,000	SD4C		ZIJIMI		INCH	Z Mics (Todis Integral)
40612	9540	Outruté-20má Value	dradoss		Word	2 bytes (18 bits not stread)
1000	000		-		1	
2 004	1,626					

	JBUS					811 0 811 0 811 0 811 0 811 0 811 1 811 1
40613	9E41	Detector measures	. 04	i di la constanti	West	Shaker (18 hite not element)
40514	9547	Averaged measure 2	1 2	Medillo 1	Word	
919	9E43	Averaged measure 3	Te 1	Module 1	Word	2 bytes (16 bits not signed)
40616	9E44	Averaged measure 4	The 1	Module 1	Word	Z bytes (16 bits not signed)
40617	9E45	Averaged measure 1	Te 1	Module 2	Word	2 bytes (16 bits not signed)
40641	9EC1	Averaged measure 1	lhe 2	Module 1	Word	2 bytes (16 bits not stored)
40642	9EC2	Averaged measure 2	lhe 2	Module 1	Word	2 bytes (16 bits not signed)
40769	9F41	Averaged measure 1	lhe 3	Module 1	Word	2 bytes (16 bits not signed)
40697	9FC1	Averaged measure 1	lhe 4	Module 1	Word	2 bytes (16 bits not signed)
41025	A041	Averaged measure 1	line 5	Module 1	Word	2 bytes (16 bits not signed)
1153	M0C1	Averaged measure 1	line 6	Module 1	Word	2 bytes (16 bits not signed)
41281	A141	Averaged measure 1	Te7	Module 1	Word	2 bytes (16 bits not signed)
	=					
41409	ATCI	Averaged measure 1	S S	Module 1	WORD	2 bytes (16 bits not signed)
41536	A240	Averaged measure 1	lhe 8	Module 32	Word	2 bytes (16 bits not signed)
41537	A241	_				
						11 2 1 2 2 2 2 3 3 3 3 3 3 3 3 3 3 3 3 3
	Snar					18 18 18 18 18 18 18 18 18
41537	A241	Maximum measure	T ed	Module 1	Word	2 bytes (16 bis not stored)
41538	A242	Maximum measure	lne 1	Module 2	П	2 bytes (16 bits not signed)
41539	A243	Maximum measure		Module 3	Word	2 bytes (16 bits not signed)
41541	A245	Maximum measure	The 1	Module 5	Word	2 pines (16 bils not signed)
	111				3	
41564	A25C	Maximum measure	9 9	Module 28	Word	2 bytes (16 bits not signed) 2 bytes (16 bits not signed)
41566	A25E	Maximum measure	The 1	Wodule 30	Word	2 bytes (16 bits not signed)
41567	A25F	Maximum measure	Te 1	Module 31	Word	2 bytes (16 bits not signed)
88	A260	Maximum measure	Te -	Module 32	Word	2 bytes (16 bits not signed)
41570	A262	Maximum measure	lhe 2	Module 2	Word	2 pites (16 bits not signed) 2 bites (16 bits not signed)
	-					
1001	AZST	Maximum measure	ne o	Module 1	WORD	Z bytes (16 bits not signed)
41633	A2A1	Maximum measure	line 4	Module 1	Word	2 bytes (16 bits not signed)
41685	M2C1	Maximum measure	lne 5	Module 1	Word	2 bytes (16 bits not signed)
41697	 A2E1	Maximum measure	lhe 6	Module 1	Word	2 bytes (16 bits not signed)
	111 A 2014	Contraction of the Contraction o	. oraș	i vine	(Control of Control	Challe to black of the contract of
4.1729	Non.	MAZIMUM INERSURE	/ 8	PACCURE 1	WOR	Z Dynes (16 Dies not signed)
41761	A321	Maximum measure	line 8	Module 1	Word	2 bytes (16 bits not signed)
792	A340	Maximum measure	lne 8	Module 32	Word	2 bytes (16 bits not stoned)
41793	A341	INSTALL BELLEVIEW	2	III DESCRIPTION OF THE PERSON	41 July 11	Annakar war ang a la ang a sa

	Mail		SIBOS		27 118 27 119 27 119 27 119 27 119 3 119 3 118	1911 3 1911 3 1911 3 1911 4
NAT Statement Direct D	Mail	41793	A341	Detector measures		
March Marc	MAY STATE STATE	793	A341	Sentence		
March Marc	March Marc	794	A342	Selferzei		
March Marc	March Marc	1/95	2000	Selliencel		
March Marc	Name	796	A344	Sentence		
ANY Content per Content	Comparison Com	787	Acto	Sellieroe		
March Sequence Control Contr	March Marc	787	Acto	Selliencel		
Name	Marcol M	798	A346	Sentence		
March Marc	A 348 Souliet Port Paris Paris	199	A347	Sentence		
Marco Britaco Britac	Name	000	A348	Sentencer		
N. M. Schiller Delicy M. M. Mark M. M. Mark M. M. M. Mark M.	March	801	A349	Senterce1		
A34 Scaletrock Parish	A34A Semilarized BM262 BM262 BM264 Control BM264 Control Contr	901	A349	Sentencer		
A34D Sentence	WASE Sentence in the control of the contr	302	A34A	Sentence1		
A3D Senietree Bytes/2	ASC Sentence of Exemple of	903	A34B	Sentence1		
A34D Senietree that the condition of the southerest conditions and the condition of the	A347 Sanietree Byto21 Earlie Byto22 Byto22 Earlie Byto22 Earlie Byto22 Earlie Byto22 Earlie Byto22 Earlie Earlie Byto22 Earlie	904	A34C	Sentence1		
A3F Sentence	A346 Seniterce Byta32 Jenn althe end of the sortions Byta32 Seniterce Seniterce Seniterce Seniterce Seniterce Seniterce Seniterce	908	A34D	Sentencer		
N3F Seniterror Byto23 / lerm at the end of the senitor Byto23 / lerm at the end of the senitor Byto23 / lerm at the end of the senitor Byto23 / lerm at the end of the senitor Byto23 / lerm at the end of the senitor Byto23 / lerm at the end of the senitor Byto33 / lerm at the end of the senitor Byto33 / lerm at the end of the senitor Byto33 / lerm at the end of the senitor Byto33 / lerm at the end of the senitor Byto34 / lerm at the end of the	National Paylocation National Paylocation	908	A34E	Sentence1		
National N	National Participation National Participat	307	A34F	Sentence	/term at the end of the sentence	
ASST Defector measures	NSS Detector measures	308	A350			
A350 Delector measures A360 Delector measures A360 Sentence2 A360 Sentence2 A360 Sentence2 A360 Sentence2 A360 Sentence2 Byte	A350 Diedeformeasures Died		2		ET 11. ST 11. OT 11. E 11. OT 11. E 11.	2 10 2 10 1 10
ASSU Senience Bytes <	ASSU Sentence2 Bytes Bytes Figs Pack ASSZ Sentence2 Brites	808	A350	Detector measures		1
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A352 Sentence2 Bytes Bytes Bytes A354 Sentence2 Bytes Bytes Bytes A354 Sentence2 Bytes Bytes Bytes A356 Sentence2 Bytes Bytes Bytes A358 Sentence2 Bytes Bytes Bytes A356 Sentence2 Bytes Bytes Bytes	A352 Sentence2 Byte5 Byte5 Byte10 A354 Sentence2 Byte17 Byte10 Byte10 A354 Sentence2 Byte17 Byte17 Byte17 A356 Sentence2 Byte17 Byte17 Byte18 A356 Sentence2 Byte17 Byte18 Byte18 A356 Sentence2 Byte17 Byte18 Byte18 A356 Sentence2 Byte21 Byte21 Byte21 A356 Sentence2 Byte21 Byte22 Byte24 A356 Sentence2 Byte23 Byte24 Byte24 A356 Sentence2 Byte23 Byte24 Byte24 A356 Sentence2 Byte24 Byte24 Byte24 A356 Sentence2 Byte24 Byte24 Byte24 A356 Sentence2 Byte24 Byte25 Byte25 A356 Sentence2 Byte24 Byte25 Byte25 A356 Byte24 Byte25	606	A351	Sentence2		
A 35.4 Sentence 2 B Med 2 B Med 3 B Med 1 B Med 2	A 353 Sentences Bytest Bytes	310	A352	Sentence2		
A354 Sentence2 Byte12 Byte12 Byte11 Byte12 Byte12 Byte13 Byte13 Byte13 Byte141 Byte13 Byte141 Byte1411	A364 Sentence2 Byte10 Byte10 Byte10 Byte10 Byte11 Byte21 Byte22 Byte22 Byte22 Byte22 Byte22 Byte23	311	A353	Sentence2		
A354 Sentence2 Byte13 Byte14 Byte14 Byte14 Byte15 Byte14 Byte15 Byte14 Byte15 Byte16 Byte15 Byte16 Byte16 Byte17 Byte18 Byte20	A354 Sentence2 Byte 13 Byte 14 Byte 15 Byte 14 Byte 15 Byte 14 Byte 15 Byte 16 Byte	312	A354	Sentence2		
A356 Sentence2 Byte15 Byte16 Byte16 Byte16 Byte17 Byte20	A356 Sentence2 Byte13 Byte16 A357 Sentence2 BYE17 BYE18 A357 Sentence2 BYE17 BYE27 A358 Sentence2 BYE27 BYE27 A359 Sentence2 BYE27 BYE27 A350 Sentence2 BYE27 BYE27 A350 Sentence2 BYE27 BYE27 A350 Sentence2 BYE27 BYE27 A350 Sentence2 BYE27 BYE27 A351 Sentence2 BYE27 BYE27 A351 Sentence2 BYE27 BYE27 A351 Sentence2 BYE27 BYE27 A352 Sentence2 BYE27 BYE27 A354 BYE27 BYE27 BYE27 A356 Sentence2 BYE27 BYE27 A357 BYE27 BYE27 BYE27 BYE27 BYE27 BYE27 BYE27 BYE27 BYE27 BYE27 BYE27	312	A354	Sentence2		
A356 Sentence2 BMe17 BMe18 BMe18 BMe18 BMe18 BMe18 BMe18 BMe20	A356 Sentence2 Byte15 Byte16 Byte16 Byte17 Byte18 Byte20	813	A355	Sentence2		
A357 Sentence2 Byte 17 Byte 17 Byte 18 Byte 18 Byte 18 Byte 18 Byte 22 Byte 22 Byte 24 Byte 24 <th< td=""><td>A357 Sentence2 Byte 19 Byte 19 Byte 19 Byte 10 Byte 10 Byte 10 Byte 10 Byte 20 <th< td=""><td>814</td><td>A356</td><td>Sentence2</td><td></td><td></td></th<></td></th<>	A357 Sentence2 Byte 19 Byte 19 Byte 19 Byte 10 Byte 10 Byte 10 Byte 10 Byte 20 Byte 20 <th< td=""><td>814</td><td>A356</td><td>Sentence2</td><td></td><td></td></th<>	814	A356	Sentence2		
A35B Sentence2 Byte20 Byte20 Byte20 A35B Sentence2 Byte21 Byte21 Byte21 A35A Sentence2 Byte21 Byte21 Byte26 A35B Sentence2 Byte27 Byte27 Byte28 A35C Sentence2 Byte27 Byte37 Byte30 A35C Sentence2 Byte37 Byte37 Byte30 A35C Sentence2 Byte37 Byte37 Byte30 A35C Sentence2 Byte37 Byte30 Byte30 A35C Sentence2 Byte37 Byte30 Byte30 A35C Sentence2 Byte30 Byte30 Byte30 A35C Byte30 Byte30 Byte30 Byte30 Byte30 A35C Byte30 Byte30 Byte30 Byte30 Byte30 Byte30 A35C Byte30 Byte30 Byte30 Byte30 Byte30 Byte30 A35C Byte30 Byte30 Byte30 <t< td=""><td>A35B Sentence2 Byte20 Byte20</td><td>815</td><td>A357</td><td>Sentence2</td><td></td><td></td></t<>	A35B Sentence2 Byte20	815	A357	Sentence2		
A356 Sentence2 BMs22 BMs23 BMs24 BMs26 BMs28 B	A356 Sentence2 B4622 B4623 B	918	A358	Senterce2		
A356 Sentence2 Byte25 Byte25 Byte26 Byte26 Byte27	A356 Sentence2 Brita24 Brita24 Brita24 Brita24 Brita24 Brita24 Brita24 Brita24 Brita26 Brita26 Brita26 Brita27 Brita	916	A358	Sentence2		
A35A Sentence 2 Byte25 Byte26 Byte26 Byte27 Byte27 Byte27 Byte27 Byte27 Byte27 Byte27 Byte27 Byte37	A35A Sentence2 Byte25 Byte26 Byte26 Byte27 Byte28 Byte27 Byte28 Byte27 Byte28 Byte27	817	A359	Sentence2		
A35B Sentence 2 Byte27 Byte29 Byte37	A35B Sentence2 Byte28 Byte28 Byte28 Byte28 Byte28 Byte28 Byte28 Byte28 Byte28 Byte32	818	A35A	Sentence2		
Max Sentence 2 Byte29 Byte29 Byte29 Byte29 Byte30	M35C Sentence2 Byte230 Byte230 Byte230 Byte320 Byte320 Byte320 Byte320 Byte320 Byte320 Byte321 term at the end of the sentence Byte321 term at the senten	819	A35B	Sentence2		
Master Byte37 Byte37 Byte37 Byte37 Byte37 Byte34 empty	A35D Sentence2 Byta31 Byta32 Byta32 term at the end of the sentence Byta31 term at the end of the end of the sentence Byta31 term at the end of th	820	A35C	Sentence2		
M35E Sentence2 Byte33 / ferm at the end of the sentence Byte34 / empty	MASSF Sentence2 Byta34 / empty B	821	A35D	Sentence2		
M3SF	M35F	822	A35E	Sentence2		
A35F Remoted keyboard A35F Branched keyboard	A3SF Remoted keyboard Remo	823	A35F			
A35F Remoted keyboard World Brit 32bytes	A35F Remoted keyboard				27 182 CT 182 OT 183 OT 183 E	2 116 2 11 2 3 11 3
A300 Blank 22bytes	A360 Blank 32 bytes	823	A:35F			1
2000	A37F	PC8	4 360			
	1	4500	2000			

SETTINGS VIA COMCPS	IA COMCPS		Byte1	Biviez
			2	
	JBUS		2 L 118 2 L 118 3 L 118 3 L 118 6 118 8 119	811 6 811 7 811 7 811 3 811 3
50001	C351	Module list		
50001	C351	Module 1 Name (32byte)	Byte 1 Name By	Byte 2 Name
		The state of the s		
50017	1983	Module type (1 byte) Relay position (1 byte)		Indice relay (1 byte)
50018	2362	Input (1 byte) Config by fault (1 byte)	(6	Config by fault (1 byte)
50019	සුස	Module 2 Name (32byte)		Byte 2 name
	0000			
50035	2223	Module type (1 byte) relay position (1 byte)		Relay position (1 byte)
90039	5274	Input Position (1 byte) Config by faut (1 byte)	Input position (1 byte)	config by fault (1 byte)
	0000			
54591	DESE	Module name 256 (32byte)	Byte 1 name	Byte 2 name
	0000			
54607	D54F	Module type (1 byte) Relay position (1 byte)	Module type (1 byte)	Relay position (1 byte)
54608	099G	Input position (1 byte) Config by fault (1 byte)	Input position (1 byte)	Config by fault (1 byte)
54609	1990			
	51101		2f 1 2f 1 2f 1 0f 1 8 1	61 61 61 81, 81,
	0000		8 8 8	8
54809	D651	Relaylist		
54609	D551	Module number (16v/e) and relay function and position (1b)	Module number (0-265)	Relay function number module
54610	D552	Relay Name, Joupput 1 (20byte) 2 bytes	Byte1 name	Byte 2 name
			┫	
54620	D65C	empty Byte	HS position	
54621	0990	slay function and position (1b)	Module number (0-255)	Relay function number Relay number on the
54622	D66E	Relay Name Joulput 2 (20byte) 2 bytes	Byte 1 name	Byte 2 name
54632	8990	HS Position / function output4-20mA (1byte) empty Byte 2 bytes	s HS Position	
57669	E145	Module number (1byte) and relay position and function (1b)	Module number (0-255)	Relay function number Relay number on the
		Relay Name Joupui256 (20byte) 2 bytes	Byte 1 name	Byte 2 name
		HS position / function output4-20mA (1byte) Empty Byte 2 bytes	s HS position	
57681	E161			

	SUBC			21 118 21 118 21 118 11 118 01 118 8 118	7 1188 6 1188 6 1188 6 1188 7
57681	E151	Imput list			
57681	E161	Module number (1 byte) and input number (1b)	П	Module number (0-255)	Relay function number Relay number on the
57802	E102	input titalie (zvioye) Medite number/4 hide) and relevit melion and resilien (4 N	2 Dyes	Bytel Name Medite pumber/0.255	Byte z Raille Delev fineton number Delev number on the
57693	E16D	_	Т	Byte1 Name	Byte 2 Name
			Г		
60431	ECOF	Module number (1 byte) and input number (1b)	Г	Byte1 Name	Byte2 Name
		Input 1 name (20 byle) relay position (1 byle)	2 bytes	Module type (1 byte)	Relay position (1 byte)
60442	EC1A				
		DETAILS AND PARAMETERS OF THE 10 TYPES OF POSSIB	PES OF POSSIBLE SENSORS (RESERVE COMCPS)	PS)	
			•		
				6: 01: 21: 21: 91:	0 : Z : Z : Z : Z : Z : Z : Z : Z : Z :
60700	JBUS	list make of the modules		118 118 118	118
SOMES	ECOL	contract of the mounts		Delot Namo	Detail Name
20400	EVE	decirality of the Lie place)		Disc Name	Directivation
60465	EC31	gaz name for type 2 (6 bytes)		Byte1 Name	Byte2 Name
60489	EC49	gaz name for type 10 (6 bytes)		Byte1 Name	Byte2 Name
00000	07.0				
60492	EC4C				
				10 11 12 13	2 5 9
	JBUS			18 18 18 18	18 18 18 18
60492	EC4C				
60492	EC4C	Gas code for type 1 and 2 (2 bytes)		Code type 1	Code Type 2
60493		Gas code for type 3 and 4 (2 bytes)		Code type 3	Code Type 4
96709		Ges code for type 9 and 10 /2 bytes)		Code fyce 9	Code Type 10
79608	1901				
			•		
	9			61 1 61 1 61 1 61 1 61 1	61 61 61 61 61 61 61 61 61
20000	2000	Postonia o more melan		8 8 8	8 8 8
60497	E051	Instantaneous alarm 1 threshold IType 1	Mord	2 bytes (16 bits not started)	-
80498	EC52		Γ		
60499	EC53			4	
			П		
90909	ECSA		╗	2 bytes (16 bits not signed)	
60607	ECSB		7	2 bytes (16 bits not signed)	
20202	2000	Installianeous alarm 2 threehold	Word	2 Dytes (16 Dits not signed)	
anono	COC		T	z nytes (to tris tot signed)	
60616	EO84	hstantaneous alarm 2 threshold Type 10	Word	2 bytes (16 bits not signed)	
00000	0		T		
80036	EC/8	Instantaneous atarm 4 theshold	Word	Z DYRES (16 DIES MOT SIGNED.)	

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	JBUS			21 118 21 118 21 118 21 118 31 118 3 118 4 118 5 118 5 118 7 118 7 118
60637	EC79	Averaged alarm threshold		
60637	6/23	Averaged alarm 1 threshold	Type 1 Word	2 bytes (16 bits not signed)
60638	EC7A	Averaged alarm 1 threshold	Type 2 World	2 bytes (16 bits not signed)
60639	EC/B		9.3	2 bytes (16 bits not signed)

60546	EC82	Averaged alarm 1 threshold	Type 10 Word	2 bytes (16 bits not signed)
60547	EC83	Averaged alarm 2 threshold	Type 1 Word	2 bytes (16 bits not signed)
60548	EC84	Averaged alarm 2 threshold	Type 2 Word	2 bytes (16 bits not signed)
60649	EC85	Averaged alarm 2 threshold	Type 3 Word	2 bytes (16 bits not signed)
99909	ECSC	Averaged alarm 2 threshold	Type 10 Word	2 bytes (16 bits not signed)
92909	ECA0	Averaged alarm 4 threshold	Type 10 Word	2 bytes (16 bits not signed)
				13 S S S S S S S S S S S S S S S S S S S
	JBUS			118
60677	ECA1	Faut Alarm Threshold		
60677	ECA1	Alarm threshold	Type 1 Word	2 bytes (16 bits not signed)
80678	ECA2	Aarm threshold	Type 2 Word	2 bytes (16 bits not signed)
62909	ECA3	Alarm threshold	Type 3 Word	2 bytes (16 bits not signed)
98909	ECAA	Alarm threshold	Type 10 Word	2 bytes (16 bits not signed)
				21: 21: 21: 21: 21: 21: 21: 21: 21: 21:
	JBUS			
60687	ECAB	Overscale Alarm threshold		
60687	ECAB	alarm value	Type 1 World	2 bytes (16 bits not signed)
88909	ECAC		2	2 bytes (16 bits not signed)
68909	ECAD	alarm value	Type 3 Word	2 bytes (16 bits not signed)

96909	ECB4	alarm value	Type 10 Word	2 bytes (16 bits not signed)

				2 5 9 9
	JBUS			
60697	ECB5	Averaged alarm delay		O before 2 of page and a second
80698	ECBB	averaged alarm 1 Delay	Type 2 Word	2 tytes (16 bits not stoned)
66909	ECB7			2 bytes (16 bits not signed)
90909	1001	memoral alarm 1 Delaw		9 halos (48 hile not element)
80607	ECBE		Type IO World	2 bytes (16 bits not signed)
80908		averaged alarm 2 Delay	Type 2 Word	2 bytes (16 bits not signed)
60909	П			2 bytes (16 bits not signed)
60616	ECC8	averaged alarm 2 Delay	Type 10 Word	2 bytes (16 bits not signed)
90939	ECDC	averaged alarm 4 Delay	Type 10 Word	2 bytes (16 bits not signed)
				2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2
	BUS			
60637	ECDD	Hysteresis Value		
60637	ECDD	Hysterests	Type 1 Word	2 bytes (16 bits not signed)
80638	ECDE			2 bytes (16 bits not signed)
60936	ECDF	Hysterests	Type 3 Word	2 bytes (16 bits not signed)
ROBAR	ECER	Helmete	Three 10	2 hidas (18 hits not almod)
00000	EVED			z nico (10 nic nico ad act)
	!			611 611 611 611 611 611 611 611
80847	JBUS FCF7	RESERVE COMODS		
60647	ECE7		Type 1 Word	Z bytes (16 bits not stoned)
60648	ECE8		2	2 bytes (16 bits not signed)
60649	ECE9		Type 3 Word	2 bytes (18 bits not signed)
80658	ECF0		Type 10 Word	2 bytes (16 bits not signed)
	BUS			311 16 311 17 311 17 311 6 311 6 311 6 311 7 311 8 311 7 311 8 31 17 31 18 31 18
60657	ECF1	Enable or disable Alarms		
60067	ECEI	Torse 1./1 botes	2 prides	TO TENE NU TO TENE SU TO TENE NU TO TENE NU TO SENI SU TO SENI SU
				4 10 16 4 10 16 4 10 16 4 10 16 4 10 1 4 10 1 5 10 16 7 10 16
80858	ECF2	Type 3 (1 byte)	Type 4 (1 byte) 2 bytes	WAS EASONS EASON
				4 aver on the ton the ton the ton the ton the ton the ton the ton the ton the ton the ton the ton the ton the ton the ton the ton the ton the ton the ton the
19009	ECF6	lype 9(1 byte) # bit= 1 enable alarm	Type 10 (1 byte) 2 bytes	2 4 4 5 5 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4

60662 60662 60663 80666	JBUS ECF6 ECF7 ECF7	Checking of the type of connected detector Type 1 (1 byte) Type 2 (1 byte) Type 2 (1 byte) Type 9 (1 byte) Type 9 (1 byte)	2 bytes (2 bytes (2 bytes (0000 delector type 3 0000 delector type 3 0000 delector type 3 0000 delector type 9 00000 delector type 9 0000 delector type 9 00000 delector type	Code detector type 2 Code detector type 2 Code detector type 4 Code detector type 4
60667 60667	JBUS ECFB ECFB	Gas name Gas name for type 1 (5 bytes)		21 Ha ST Ha CT HA	日本 1
60659 60670 60671 60691	ECFE ECFE ECFF ED13	Gas name for type 1 and 2 (5 bytes) Gas name for type 2 (5 bytes) Gas name for type 2 (5 bytes) Gas name for type 10 (5 bytes)		Norm 1 Byte 5 raine 2 Byte 2 raine 2 Byte 4 raine 10 Byte 4 raine 10 Byte 4 raine 10 Byte 4 Na	name 2 Byte 1 name 2 Byte 3 name 2 Byte 5 Name 10 Byte 5
60692 60692 60699	JBUS ED14 ED18	Gas shortened name Gas name for type 1 (16 bytes) Gas name for type 2 (16 bytes)		CT 118 CT 118 OT 118 E 118 S 149	田
60772 60772 60773 60776	JBUS ED64 ED65 ED65	Display format Type 2 (1 byte) Type 2 (1 byte) Type 3 (1 byte) Type 4 (1 byte) Type 6 (1 byte) Type 9 (1 byte) Type 9 (1 byte) Type 10 (1 byte) T	2 bytes 2 bytes 2 bytes	Display format code type 3	本

0.18				_	0.18				
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1118	П	1eaenunsm.SIA=f	Jesen umern SIA=f	teset unsm∑lA=f	118		eve roni ⊈A=0	1evs tori SIA=0	neve nori ⊈A=0
2 118	П	fesenunsm.8M=f	teset unem člA=t	1eaen umarm 8M=f	Z 18		0=AB incrave	1evs nori 8lA=0	neva noriaVer
E #E	П	teaerunam AlA=t	teser unem MA=t	feser unem MA=t	818		neveroni≱kA=0	neverani ≱lA=0	neveroni MA=0
1719		J=overrange	абившело=р	абивше∧о=µ	t 18		evsnonihlA≕0	tevetoniflA=0	te vertoni NA=0
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7 118					7.18		neveroni≱kA=0	nevs noni ≱IA=0	neveroni MA=0
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6 113			jeserunem SIA=t	ieserunem SIA=f	6 18		leve nori 2lA=0	neve tori SIA=0	neve roni SIA=0
or ha			jeserunem 8lA=t	jesenunem ElA=t	0118			neve nori 8lA=0	0=AB incraver
rr 118			1eserunam MA=t	ieserunem AM=t	rr 18			neverani t⊾lA=0	neveroni MA=0
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111111111111111111111111111111111111111					1118			1evs 1ori 8lA=0 1evs 1est 8lA=0	0=AB incraver
ar 118					ar 18			neve oni blA=0	Teve ani MA=0
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JBUS	69CE	6D69	ED6A	EDSD	JBUS	39C3	EDSE	EDBF	ED72
	11108	11109	8778	60781		60782	28709	60783	60786
-	ω	φ	9	9	ı 1	100	9	9	9

	JBUS			21 118 21 118 3 118 6 11
60787	ED73	Reserve COMCPS		
60787	ED73	Type 1 (1 byte)	Type 2 (1 byte) 2 bytes	
60788	ED74	Type 3 (1 byte)	Type 4 (1 byte) 2 bytes	
60791	ED77	Type 9 (1 byte)	Type 10 (1 byte) 2 bytes	
				S IN COLUMN 1
	JBUS			1 118 1 118 1 118 1 118 1 118 2 118 2 118 2 118 2 118 2 118
60792	ED78	Alarm Delay		
60792	ED78	Aarm 1 Delay	Type 1 Word	2 bytes (16 bits not signed)
60793	ED79	Alarm 1 Delay	Type 2 Word	2 bytes (16 bits not signed)
60794	ED7A	Aarm 1 Delay	Type 3 Word	2 bytes (16 bits not signed)
60801	ED81	Aarm 1 Delay	Type 10 Word	2 bytes (16 bits not signed)
60602	ED82			2 bytes (18 bits not signed)
60803	ED83			2 bytes (16 bits not signed)
60604	ED84	Alarm2 Delay	Type 3 Word	2 bytes (16 bits not signed)
60811	ED8B	Alarm2 Delay	Type 10 Word	2 bytes (16 bits not signed)
60831	ED9F	Alarm 4 Delay	Type 10 Word	2 bytes (16 bits not signed)
				0 1 2
	BUS			1 118 1 118 1 118 1 118 1 118 2 118 2 118 2 118 1 118
60832	EDA0	Detector type Range		
60832	EDAO	Range	Type 1 Word	2 bytes (16 bits not signed)
60833	EDA1	Range	2	2 bytes (16 bits not signed)
60834	EDA2		Type 3 Word	2 bytes (16 bits not signed)
60841	EDA9	Range	Type 10 Word	2 bytes (16 bits not signed)

INDUSTRIAL SCIENTIFIC

DECLARATION DE CONFORMITE CONSTRUCTEUR Manufacturer Declaration of conformity

OLDHAM



La Société Industrial Scientific Oldham, ZI Est 62000 Arras France, atteste que le matériel neuf : (The Company Industrial Scientific Oldham, ZI Est 62000 Arras France, declares that the new material)

Système de Mesure CPS - Monitoring system CPS

Incluant la centrale de mesure, les détecteurs de gaz, les modules E/S et Relais (Including the control unit, the Gas detectors, the Relays and I/O modules)

est conforme aux exigences de: (comply with the requirement of:)

I) Directive Européenne CEM 89/336/CEE du 3/05/89 : Compatibilité Electromagnétique

The European Directive EMC 89/336/CEE of 3/05/89: Electromagnetic compatibility

Normes harmonisées appliquées : (Harmonised applied Standards)

EN 50270

(type 1 & 2)

II) Directive Européenne Basse Tension DBT 2006/95/CE du 27/12/06

The Low Voltage European Directive LVD 2006/95/CE 27/12/2006

Normes harmonisées appliquées :

EN 61010-1

(Harmonised applied Standards)

III) Norme de performance métrologique

(Metrology performance standard)

Normes appliquées :

VDI 2053 Annex2, Mesure du CO (CO measurement)

(Applied Standards)

▲ TÜVRheinland® (Köln, Germany)

Organisme certificateur : (Certification body)

Precisely Right.

(Certification body)

S274 2007 T1

Rapport d'essai: (Test Report)

Arras, le 05/11/08

Lionel Witrant

AF AQ 150 9001 VERSION 2000

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Directeur Technique Engineering Director

CE/CEM-DBT-104

Garanty

1 Plus Points

To respond quickly and efficiently to your consultancy needs or order tracking throughout the world via our customer service department.

To respond as rapidly as possible to all questions of a technical nature.

2 Quality

To assure you of the best quality of our products and service in conformity with the international standards and directives in force.

3 Inspection and Reliability

To provide you with reliable equipment. The quality of our production is an essential condition for this reliability. This is guaranteed by virtue of very strict checks that are carried out when raw materials come in, both during the course of and at the end of manufacture (all equipment that is sent out is configured to your individual requirements).

4 Commissioning

If required, to commission your equipment by our Ism-ATEX qualified specialists.

5 Training

To provide detailed training programs.

6 Project department

Our team will investigate all gas and flame detection projects via on-site investigations or from drawings. We can suggest pre-project studies, design, installation and maintenance of safety systems in ATEX or non-ATEX zones with full respect of all standards in force.

7 Maintenance contract

To suggest rolling maintenance contracts tailored to your needs in order to guarantee you maximum safety:

- One or more annual visits, including consumables
- · Renewable by agreement
- · Including adjustment of fixed or portable gas detectors, and inspection of control systems.

8 On-site repair

To rapidly send our Service Technicians to you. This is possible on account of our hubs in France and abroad.

9 Factory repair

To deal with any problem that cannot be resolved on-site by dispatching the equipment back to the factory. Teams of technicians will work on repairing your equipment as quickly as possible, thereby reducing the time spent out of commission to a minimum. Cost efficient replacement solutions are available if equipment is deemed not repairable. For all After Sales Service in France, contact us by email at servicecenter@oldhamgas.com

Or by telephone at + 33 (0)3 21 60 80 80. For locations near you, please visit us at indsci.com and click on the Oldham Division.

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Preserving human life on, above and below the earth Delivering highest quality, best customer service... every transaction, every time.



The Fixed Gas Detection People

EUROPEAN PLANT AND OFFICES

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